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DEVELOPMENT AND ANALYSIS OF A CVA AND A 1052 CLASS FAST FRIGATE AIR WAKE MODEL

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SUMMARY

This report documents two ship airwake turbulence models which have been developed to aid in the analysis and simulation of the shipboard launch and recovery dynamics of conventional and VSTOL aircraft. The two computer subroutines represent a large deck carrier and a FF 1052 frigate air wake. The carrier model has been used extensively for automatic carrier landing simulations. The frigate airwake model has been developed more recently and has not been widely tested. The FF 1052 airwake model has been installed as part of the NAVAIRDEVCEN VSTOL Launch and Recovery Program described in reference (a). The model has been analytically validated against wind tunnel data, but it has not been tested in a piloted simulator.

These two models are being documented in the hope that they may form the basis for a standardized method of simulating turbulence for shipboard launch and recovery analysis.

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INTRODUCTION

Two turbulence model algorithms have been developed for use in the design and analysis of conventional and vertical take-off aircraft. These are an attack carrier model (CVA) and a FF 1052 frigate model. The CVA model has been used since 1971 in the simulation of manual and automatic landings aboard large deck carriers. This model has been used at the NASA Ames Research Simulation Facility in piloted simulations of the F-14, A-7, and EA-6B aircraft. References (b) and (c) describe the data and equations used to develop the model. Free air turbulence, steady, and unsteady burble components are combined to produce the complete CVA model. To make the algorithm more suitable for VSTOL aircraft, several changes have been made from the form described in reference (c). These are as follows:

- 1. The ship airwake velocity components are programmed to exponentially decrease in magnitude beyond specified bounds of altitude and lateral position.
- 2. The vertical component of the steady air wake has been changed to include an upwash near the bow. This was inferred from time histories of AV8A launches aboard the U.S.S. Roosevelt. (See figure 1.)
- 3. An option to provide discrete gust sinusoids in place of the ship air wake model has been added. These inputs follow the form described in reference (f).

The model is limited to cases where the wind is aligned with the landing deck. Wind velocity is specified by setting the ship speed variable, VS.

The second model has been developed exclusively for VSTOL aircraft and is intended to represent wind conditions near an FF 1052 frigate.

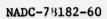
The turbulence algorithm was developed from data derived from the wind tunnel test of a 1/50 scale FF 1052 ship model. These data are contained in reference (d). The structure for the algorithm was based on work performed by the Vought Corporation and described in reference (e). However, the model described herein has been modified from the original format as a result of additional analysis of the data contained in reference (d). The model described herein is a somewhat refined version of the Vought model.

This model was programmed on the NAVAIRDEVCEN CDC 6600 computer. The Fortran listings included in this report represent the present status of the two models.

The subroutines have been tested in batch mode runs and are considered to be reasonably accurate. However, the author takes responsibility for any deficiencies that may still remain in the code.

The FF 1052 air wake model was examined by computing time histories, power spectra, and probability distributions and then comparing these with the wind tunnel velocity time histories.

This report describes all work done to validate and adjust the FF1052 model to agree with wind tunnel data. Both the CVA model and the FF1052 model are offered for inspection, use, and criticism.



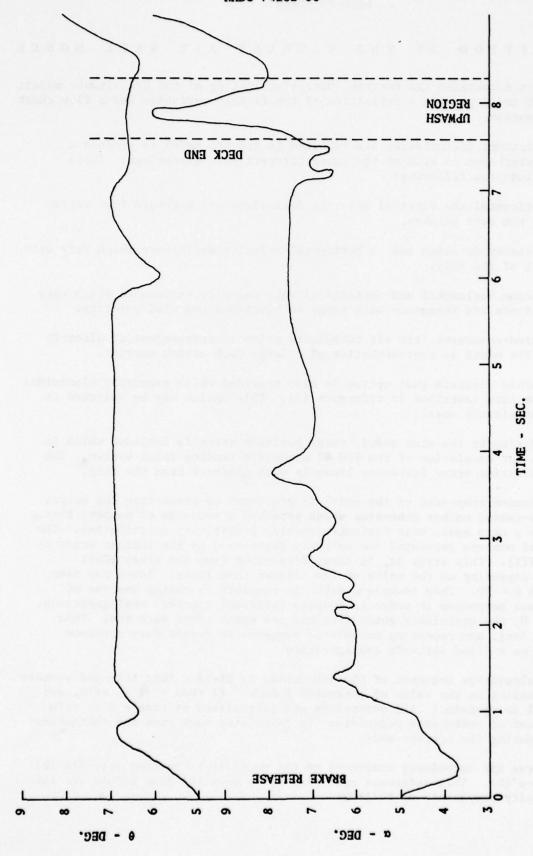


Figure 1 - Pitch Attitude and Angle of Attack During STO Launch

DESCRIPTION OF THE CARRIER AIR WAKE MODEL

Appendix A contains the Fortran subroutine listing of the CVA airwake model. Appendices B and C provide a definition of the Fortran variables and a flow chart of the subroutine.

Four distinct disturbances are combined in the CVA model to produce a velocity disturbance in each of the three aircraft axis directions. These sources include the following:

- 1. Horizontal and vertical velocity deviations which result from vortex shedding as the deck pitches.
- 2. A steady downwash and a horizontal velocity deficiency which vary with distance aft of the ship.
- 3. Random horizontal and vertical airwake velocity components which vary in RMS amplitude and frequency with range to touchdown and wind velocity.
- 4. Three-component free air turbulence which is independent of aircraft position. The model is representative of a large deck attack carrier.

A separate discrete gust option is also provided which generates sinusoidal gusts of the form described in reference (f). This option may be selected in place of the airwake model.

In addition to the wind model, radar position error is included which is appropriate for simulation of the SPN-42 automatic landing radar system. The simulated position error increases linearly with distance from the ship.

Each random component of the model is generated by processing the output of a pseudo-random number generator which produces a sequence of numbers that approximate a zero mean, unit variance Gaussian probability distribution. The sequences of numbers generated are uniquely determined by the integer start up array IRDST(I). This array is, in turn, determined from the array IRDSI (I, Ionce) depending on the value of the integer flag Ionce. Ionce may take values from 0 - 10. This technique makes it possible to repeat any one of 10 turbulence sequences in order to compare different aircraft configurations. If Ionce = 0, the turbulence generators are not reset after each run. This produces a long, non-repeating turbulence sequence to gather more accurate statistics on a fixed aircraft configuration.

The calculation sequence of the subroutine is divided into trim and operate modes depending on the value of parameter I Mode. (I Mode = -1 in trim, and I Mode = +1 in operate.) All parameters are initialized at time = 0 in trim and a new set of turbulence velocities is calculated each time the subroutine is called during the operate mode.

The free air turbulence component of the model is taken from appendix (b) of reference (h). This reference specifies power spectral gust models for the three velocity components as follows:

$$\phi \frac{\Delta u}{v_0} = \frac{200/v_0^3}{\left(\frac{S}{v_0/100} + 1\right) \left(\frac{-S}{v_0/100} + 1\right)} \frac{(ft/sec)^2}{(rad/sec)}$$

$$\phi \stackrel{\Delta v}{=} \frac{\left(\frac{5900}{v_o^3}\right) \left(\frac{S}{v_o/400} + 1\right) \left(\frac{-S}{v_o/400} + 1\right)}{\left(\frac{S}{v_o/1000} + 1\right) \left(\frac{-S}{v_o/1000} + 1\right) \left(\frac{S}{3v_o/400} + 1\right) \left(\frac{-S}{3v_o/400} + 1\right)} \frac{\frac{(ft/sec)^2}{(rad/sec)}}{\left(\frac{S}{v_o/1000} + 1\right) \left(\frac{-S}{3v_o/400} + 1\right)}$$

$$\phi \frac{\Delta w}{v_0} = \frac{71.6 / v_0^3}{\left(\frac{S}{v_0/100} + 1\right) \left(\frac{-S}{v_0/100} + 1\right)} \frac{(ft/sec)^2}{(rad/sec)}$$

The corresponding root-mean-square gust amplitudes are:

uG = .76 M./sec (2.5 ft/sec)

 $W_G = .457 \text{ M./sec (1.5 ft/sec)}$

 $v_G = .728 \text{ M./sec } (2.39 \text{ ft/sec})$

The frequency parameters of the free air turbulence filters are determined by the trim airspeed v_0 . Since the algorithm was developed for conventional flight simulation, the equations do not permit the direct substitution of zero airspeed for a hover case. For low trim speeds, the parameter is arbitrarily set to 18.29 M./sec (60 ft/sec). This value was selected as a reasonable estimate of the maximum relative wind over a moving ship.

The turbulence routine options are determined by selecting integer flag parameters as either 0 or 1. The normal values of these flags are as follows:

Iwind = 1

ILburb = 1

ILturb = 1

IBfrz = 0

Idisct = 0

Iubt = 0

Ivbt = 0

Iwbt = 0

This produces a complete ship airwake model for approach simulation. The complementary values produce these effects:

Iwind = 0 Return all zero turbulence values.

ILburb = 0 Select alternate downwash function.

ILturb = 0 Set all free air turbulence components to zero.

IBfrz = 1 Fix turbulence range variable to xd = xfrz.

Iubt = 1 Set u component of airwake burble to zero.

Ivbt = 1 Set v component of airwake burble to zero.

Iwbt = 1 Set w component of airwake burble to zero.

Idisct = 1 Select discrete gust options in place of carrier airwake model.

The ship dependent portion of the airwake was developed primarily from water tunnel tests of CVA ship models. The steady components consist of tabulated values of horizontal and vertical velocity functions ($\Delta u/vs$ and $\Delta w/vs$) versus range. These functions are shown in figure 2. The downwash and reduction in relative wind is determined by multiplying the tabulated functions by ship speed vs. The model assumes that all the wind is generated by the ship and that the velocity is aligned with the landing deck.

Periodic wind components with magnitudes proportional to ship pitch are also included. These sinusoidal vertical and horizontal components propagate aft from the ship at 85 percent of the ship speed and decay in amplitude with range.

The apparent frequency at which the velocity varies is determined by the aircraft closing speed according to formula

Magnitude = cosine
$$\left[\omega_p\left(1. + \frac{\Delta v}{0.85 \cdot v_s}\right) \cdot t + \frac{x_d}{0.85 \cdot v_s} + \phi - 1.57\right]$$

where ω_p = ship frequency, Δv = aircraft closing rate, v_s = ship speed, x_d = distance to ship cg, and ϕ = phase.

The magnitude of the sinusoid decreases linearly with distance aft of the ship. The burble is set to zero outside of established limits fore and aft of the ship. Additional limits on magnitude are established by altitude and lateral position of the aircraft. The magnitude is assumed to decrease exponentially at distances greater than 100 feet to the left or right of the ship and at altitudes greater than 50 feet above the deck. Reference (i) indicates that the burble is largely restricted to this region.

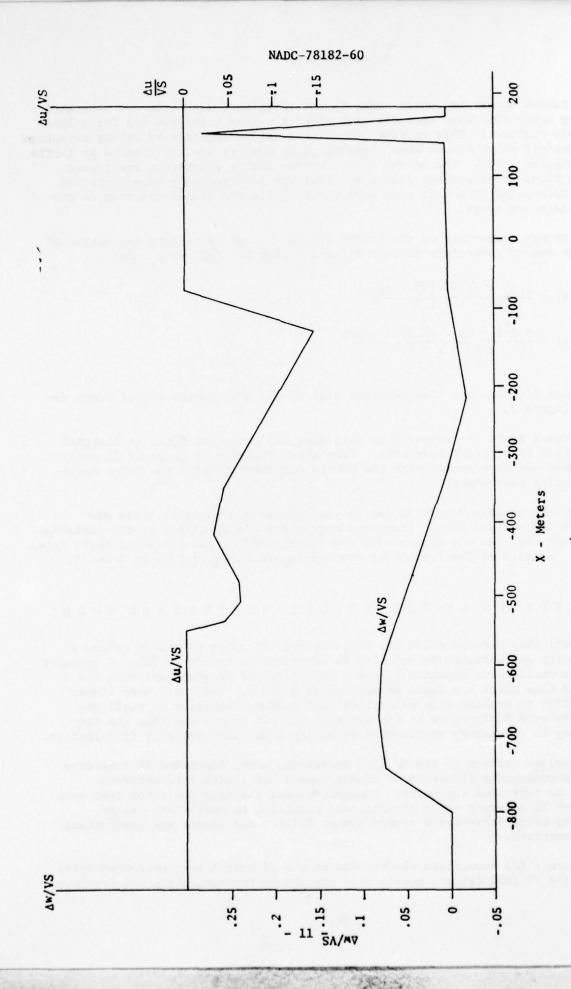


Figure 2 - CVA Ship Burble Steady Wind Ratios

The random number sequences used by the turbulence algorithm are generated by calling subroutine Rand once for each element. (See reference (a) for a listing of this routine.) This routine senerates a random sequence by taking advantage of the roundoff which occurs when floating point numbers are represented by finite length computer words. The output of the random number generators are passed through a first-order washout filter to eliminate low-frequency components and are then multiplied by a unit sine wave which shifts the signal spectrum to the desired frequency range.

The random components of the burble are determined by passing the output of the random number generators through filters having the following form:

$$ub2(s) = \frac{\delta(X) \cdot \sqrt{2 \cdot \tau(X)} \cdot Input}{\tau(X) \cdot s + 1.0}$$

wb2(s) =
$$\frac{0.035 \cdot VS \cdot \sqrt{6.66} \cdot Input}{3.33 \cdot s + 1.0}$$

The variance $\delta(x)$ and the time constant $\tau(x)$ of the u component versus range are shown on figure 3.

The total burble is computed in ship axes and converted first to inertial axes and then to aircraft body axes. Free air turbulence is computed directly in body axes and then summed with the burble component to give the total turbulence velocity components.

When the variable Idisct is set to one, discrete sinusoidal gusts are calculated in inertial axes. Component magnitudes are specified by the variables Vmn, Vme and Vmd, and the frequencies are established by the variables Frth, Frte, and Frtd. Samples of the turbulence components are shown in figures 4 and 5.

DESCRIPTION OF THE FF1052 TURBULENCE MODEL

A small ship airwake model has been constructed using tabulated values of mean velocity and variance in velocity as described in reference (d). A computer listing is included in appendix D, and a definition of program variables and a subroutine flow chart are found in appendices E and F. The model uses linear superposition to combine mean velocities with random velocities to yield the total turbulence disturbance at the aircraft cg. It is assumed that the turbulence may be adequately represented as having a Gaussian velocity distribution.

An earlier version of the FF 1052 turbulence model described in reference (e) used second-order filtering of random inputs and cosine extrapolation functions to represent the gusts. However, recent analysis indicates that some improvement in accuracy and a simultaneous reduction in complexity can be achieved by using first-order random number filters and linear and exponential shaping functions.

Reference (d) summarizes the results of a wind tunnel test performed using a 1/50 scale FF 1052 frigate model. The turbulence representation was developed

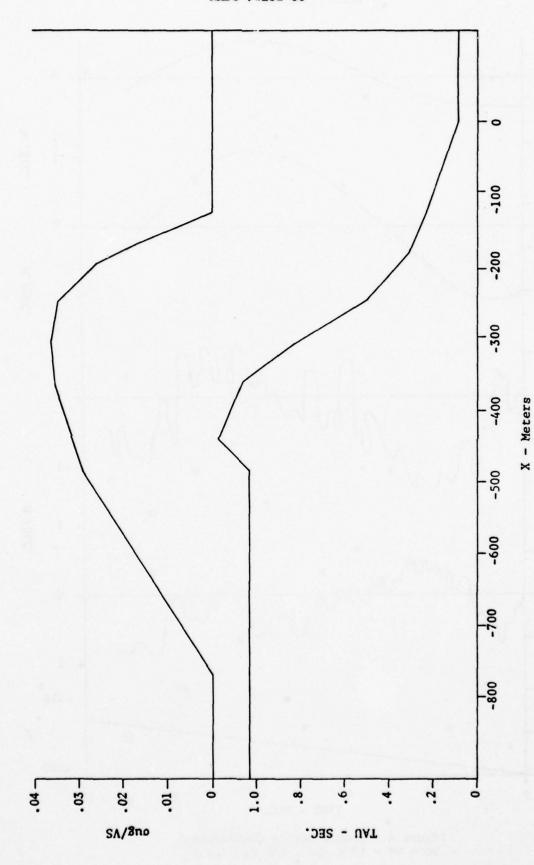


Figure 3 - U Component Burble Time Constant and Variance

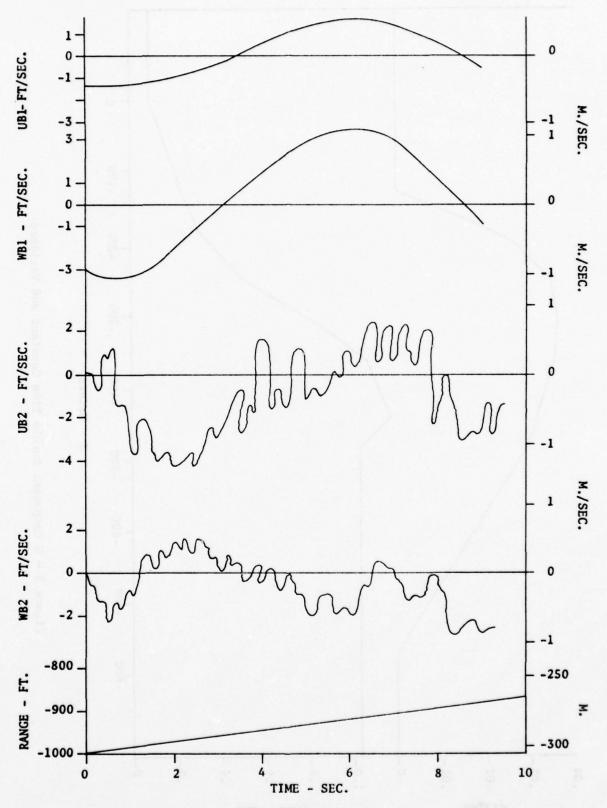


Figure 4 - Sample Burble Components VO = VS = 18 M./Sec. (60 Ft./Sec.)

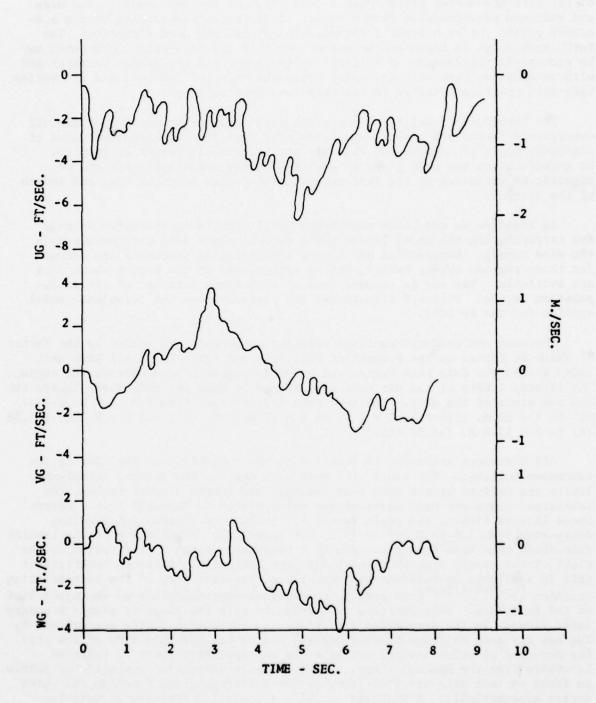


Figure 5 - Sample of CVA Simulated Free Air Turbulence

from statistical summaries of the measured turbulence velocities which define the mean and variance of the three velocity components recorded by an array of hot wire anenometer probes placed downstream of the ship model. The mean and variance were computed from a series of 262 measurements made over a 1.6-second period for each probe location, wind speed, and wind direction. The turbulence model is based on the assumption that the full-scale turbulence may be accurately represented as filtered white noise with the proper variance and with an additive mean velocity value where the value of the mean and the varian vary with position relative to the ship touchdown bullseye.

The turbulence model assumes a point mass aerodynamic model in which all aerodynamic forces and moments are calculated from the instantaneous value of airspeed, angle of attack, and sideslip at the aircraft center of gravity. No consideration has been given to either unsteady aerodynamic effects or significant variation in the instantaneous velocities over the span and length of the aircraft.

In addition to the basic turbulence model structure, provision is made for extrapolating the model beyond those regions where data were measured in the wind tunnel. Exponential and linear extrapolation functions are assumed for those regions above, behind, and to either side of the region where data are available. The air is assumed free of turbulence outside of the extrapolation region. Figure 6 illustrates the regions where the turbulence model applies for the FF 1052.

The mean and random turbulence velocity components are scaled by the factor F1 which is formed as the product of Fx1, Fy1, and Fz1. These all have unit value within the data base region and smoothly approach zero outside the region. The lateral limits of the air wake are defined by Ymax and Ymin which locate the bow and stern of the ship. The test data base extends from Y = -5.7 M. (-18.75 ft) to Y = 52 M. (170 ft), X = 0 M. to X = 76 M. (250 ft), and Z = 4.4 M. (14.58 ft) to Z = 13.6 M. (44.58 ft).

All distances are measured relative to the instantaneous location of the touchdown bullseye. For small wind over deck angles, the lateral turbulence limits are defined by the data base limits. For larger heading angles, the tabulated values are held constant and extrapolated to Ymax and Ymin. Beyond these lateral limits, the scale factor Fyl follows an exponential function decreasing from 1.0 to 0.367 (e-1) in one beamwidth. Examination of the tabulatdata shows that this function produces a reasonable match in the region to the right of the center line where most data are available. Although insufficient data is available to validate the assumption, the same form of the extrapolating function $\begin{pmatrix} e^{-(H-Ho)/Beam} \end{pmatrix}$ is used to extrapolate vertically beyond the upper limi of the test data. This function is consistent with the shape of simple boundary layer flows. In the streamwise direction, the turbulence limits are defined by the bow for zero relative heading angles, and by the upstream side of the ship for non-zero relative heading angles. The extrapolation limit is extended laterally from the bow and stern. All turbulence velocities computed for points in front of this line are diminished by the X extrapolation function Fxl which decays exponentially. A linearly scaled extrapolation function is used for Fxl aft of the data base limit of 76 M. (250 feet).

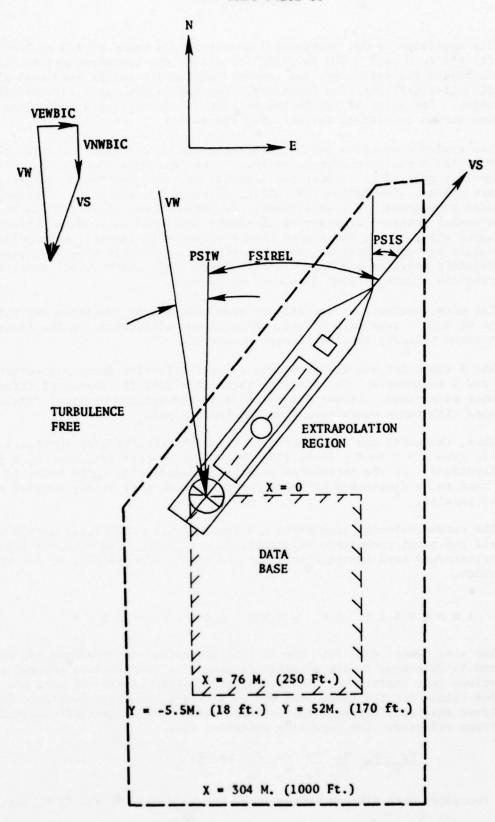


Figure 6 - FF 1052 Ship Airwake Model Geometry

The amplitude of Fx1 decreases linearly from a value of 1.0 at X = 76 M. (250 ft) aft to 0 at X = 305 M. (1000 ft) aft of the touchdown point. In the regions beyond the data base, the nearest tabulated value is used with the multiplicative extrapolation function F1 applied to the value returned from the tables. The slope of Fx1 in the aft region was suggested from plots of variance versus downstream range. (See figure 7.)

The random components of the turbulence are produced by filtering the output of these random number generators. The frequency content of the turbulence is regulated by varying the interval at which the random number generators are called. Increasing the calling interval decreases the frequency of the simulated turbulence. For an aircraft simulation interval of 0.05 second, a random number interval of 0.3 to 0.35 second was found to produce a reasonable turbulence simulation. The random number sequence is linearly interpolated for time values between succeeding calls to produce a smoothly varying number sequence. This sequence provides the input to first-order lags which effect additional filtering and eliminate high frequency variations.

The time constants of the filters were selected by examining the power spectra of sample test data points. Significant differences in the frequencies of the three velocity components were uncovered.

The X component was found to have a lower effective frequency content than the Y and Z components. In addition, there is a definite change of turbulence frequency with range. It was determined that the maximum spectral frequency decreased with range downstream from the landing pad.

Thus, the model was constructed to allow the three filter constants to vary linearly from X = 0 to X = 58 M. (190 ft). This appears realistic from physical considerations. As the turbulence propagates downstream, rapid velocity fluctuations tend to be diminished by shear forces whereas more slowly varying velocities tend to persist.

The random velocity components are combined with the steady mean components to yield the total turbulence velocities in wind axes. These velocities are then transformed into inertial axes for use by the main portion of the aircraft simulation.

ANALYSIS OF WIND TUNNEL DATA

The wind tunnel data for the FF 1052 summarized in reference (d) were analyzed to determine if any significant trends or correlations existed among the various test conditions. An attempt was made to reduce the mean and variance values for the three wind speeds tested to nondimensionalized functions. To achieve this end, the mean and variance values were nondimensionalized by the freestream velocity. The resulting functions were

$$\frac{v_x - v_{\infty}}{v_{\infty}}$$
, $\frac{v_y}{v_{\infty}}$, $\frac{v_z}{v_{\infty}}$, $\frac{\delta x}{v_{\infty}}$, $\frac{\delta y}{v_{\infty}}$, and $\frac{\delta z}{v_{\infty}}$.

These functions were plotted versus range for V = 10, 18, and 23 M./sec.

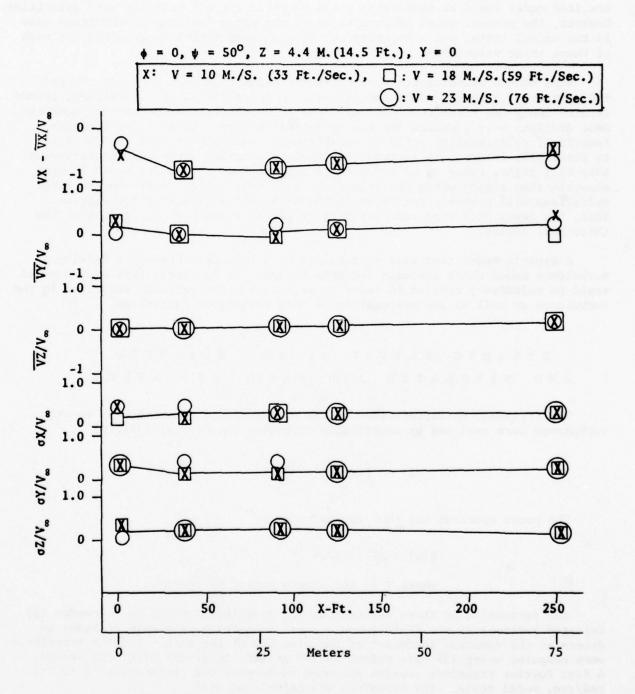


Figure 7 - Nondimensionalized Turbulence Parameters Versus Range

Figure 7 illustrates these functions. It can be seen that the nondimensionalized functions for the three velocities agree rather well. This suggests that a generalized model could be used which would be valid for all relative wind velocities. However, the present model is restricted to the three freestream velocities used in the tunnel tests, and a separate set of nonlinear tables is required for each of these three velocities.

Wind tunnel measurements were taken for model roll angles of -30, 0, and +30 degrees. These data were investigated to determine if any significant trends existed among the three roll angles. Mean and variance size at various measurement stations were compared for the three roll angles. However, no definite functional relationships could be established. Although it would be possible to statically interpolate between the three roll angles given the instantaneous ship roll angle, there is no evidence to suggest that this model would be more accurate than simply using the values for zero roll angle. Furthermore, air operations will probably not be attempted with roll angles near ±30 degrees. Thus, the level deck wind velocity data is probably the most applicable of the three roll angles.

A dynamic model test will be required to obtain data needed to develop a turbulence model which accounts for ship motion. It is likely that such a model would be relatively complex in order to account for the periodic variation in the turbulence as well as the propagation of this turbulence downstream.

DYNAMIC NATURE OF THE MEASURED AND SIMULATED AIR WAKE TURBULENCE

The frequency characteristics of the simulated and measured wind tunnel turbulence were analyzed by numerically computing the Fourier integral

$$X(J\omega) = \int_0^T X(t) e^{-J\omega t} dt$$
.

The power spectrum was then approximated as

$$S(\omega) \simeq \frac{1}{2T} \mid X(J\omega) \mid^2$$

where T is the sample period in seconds.

The derivation of these expressions are described further in reference (g). Selected portions of the FF 1052 wind tunnel turbulence data were analyzed to determine the spectral character of the wind aft of the ship. Fourier transforms were computed using 256 data points spaced at time intervals of 0.0061 second. A fast Fourier transform routine was used to compute the spectra from 0 to 515 rad/sec. model scale. The transform was calculated with

$$\Delta \omega = \frac{2 \cdot PI}{Nsamples}$$
 rad./sec. and

maximum frequency =
$$\frac{PI}{AT}$$
 = 515 rad./sec.

TABLE I
Selected Wind Tunnel Test Points Used in Spectral Analysis

Yaw (deg.)	Roll (deg.)	Speed (M/S)	X (Meters)	Y (Meters)	Z (Meters)
30	9	9	0	0	4.2
50		9	Ī	0	4.2
50		9		0	7.6
0		16		5.5	4.2
0		16		0	4.2
0		16		0	7.6
30		16		5.5	4.2
30		16		0	4.2
30		16		0	7.6
50		16		0	4.2
50		16		0	7.6
0		22		5.5	4.2
30		22	ŏ	0	4.2
30		9	11		4.2
30		9	Î		7.6
50		9			4.2
50		9			7.6
30		16			7.6
30		23	11		4.2
30		10	27		4.2
30	Ŏ	18	27	ŏ	4.2

TABLE II

Statistics of Frequency Value Corresponding to Maximum of Spectra Grouped by Velocity and Velocity Component

Freestream Velocity			Frequency - Rad/Sec.			
M./S.	(ft/sec)	Component	Average	Maximum	Minimum	RMS
9.1	30	x	60	110	30	30
9.1	30	Y	76	110	10	34
9.1	30	Z	90	150	30	43
16.46	54	x	95	190	10	52
16.46	54	Y	108	260	10	99
16.46	54	Z	140	290	30	90
21.9	72	х	90	170	30	58
21.9	72	Y	130	170	70	43
21.9	72	z	290	410	150	107

TABLE III

Statistics of Peak Spectral Velocity Grouped by Velocity Only

Velocity		Peak Spectral Frequency - Rad/Se			ec.
M./S.	(Ft./Sec.)	Average	Maximum	Minimum	RMS
9.1	(30)	75	150	30	45
16.46	(54)	114	290	15	80
21.9	(72)	170	410	30	114

Because the number of samples was relatively small, the power spectra were generally very erratic. The data were thus smoothed by averaging over groups of six succeeding frequency points. Figures 8 to 10 illustrate samples of the smoothed spectral data. The sample cases shown in table I were examined with regard to spectral content.

These data were analyzed to determine if any significant trends existed with respect to the spectral distributions. The frequency at which the spectrum attained its maximum value was computed for each case and the data were sorted according to freestream velocity and velocity component. The maximum, minimum, average, and RMS value of the frequency at which the peak of the spectrum occurs is tabulated in table II.

Grouping the data by freestream velocity only, the frequency statistics can be summarized as shown in table III.

Figure 11 summarizes the frequency trend as a function of test condition velocity. A least squares fit of the three gross averaged frequencies yields the relation

$$\omega _{\text{test}}^{\text{max}} = 3.837 + 2.2274 \cdot V - rad/sec.$$

Strouhal scaling based on model length is used to obtain the equivalent full-scale frequency as

$$\omega$$
 max full scale = 0.07674 + 0.04548 · V - rad/sec.

For the test velocities, this becomes

TABLE IV
Turbulence Frequency Versus Airspeed

<u>ω - Full Scale</u>	V - Ft./Sec.
1.440	30
2.76	59
3.53	76

This differs from the second-order filter model frequency of 1.9 rad./sec. at V = 18 M./S. (59 ft./sec.) as described in reference (d). If additional wind tunnel data is unavailable, the FF 1052 model may be applied to larger or smaller ships having similar geometry or the same ship at different velocities by applying Strouhal scaling, where

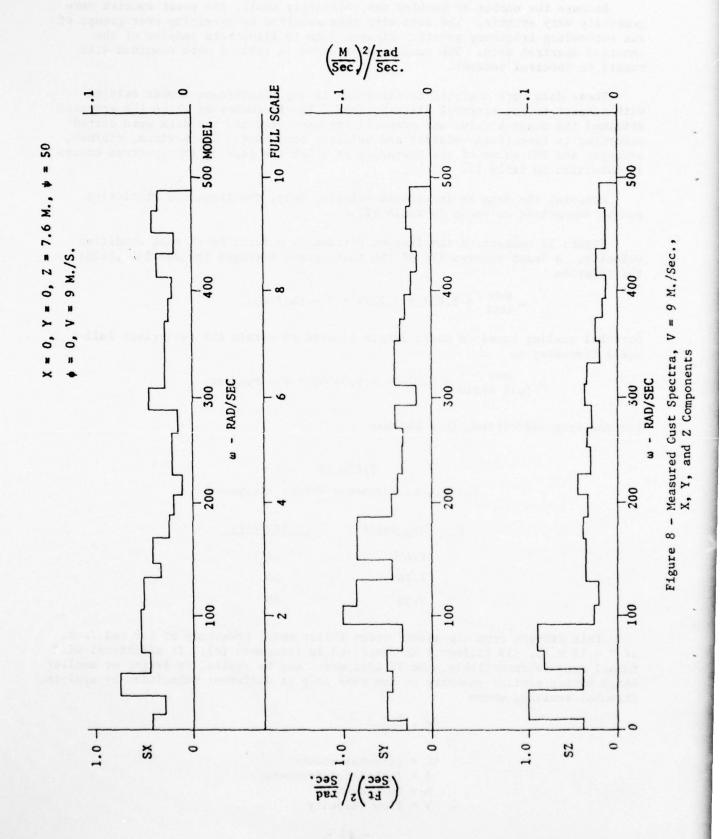
$$SN = \frac{f \cdot h}{V}$$

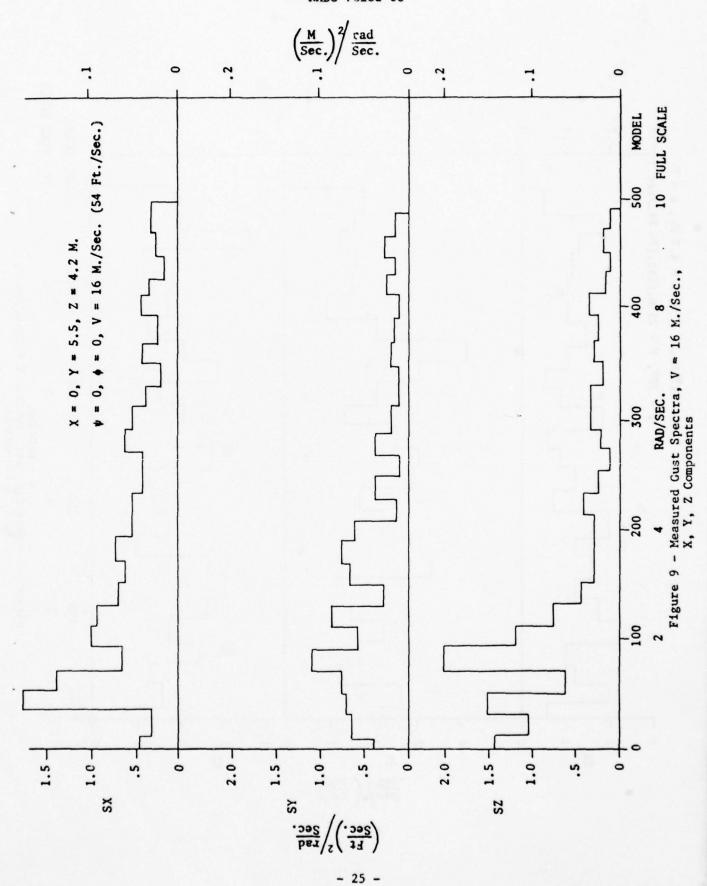
SN = Strouhal number

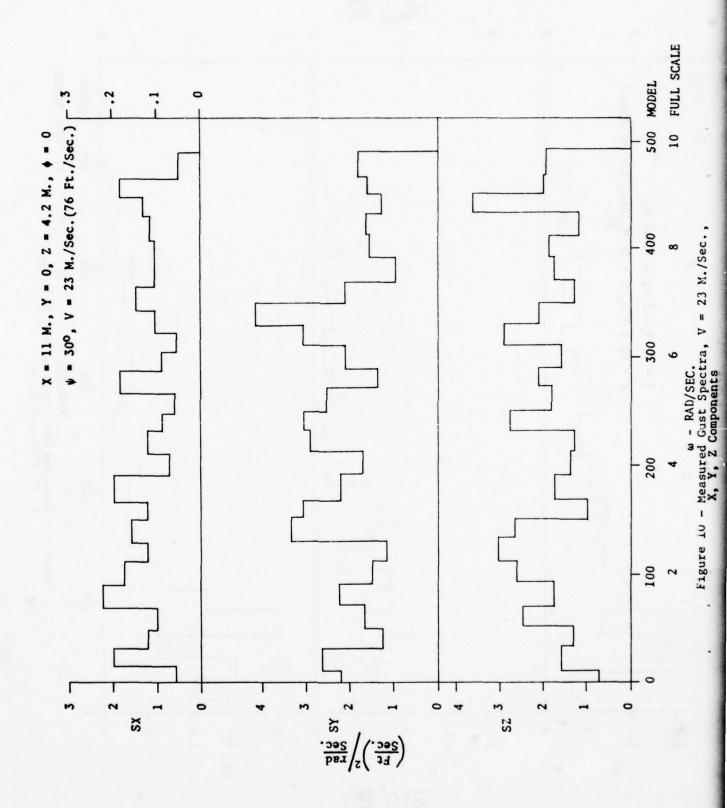
f = Turbulence frequency

h = Ship beam

V = Flow velocity







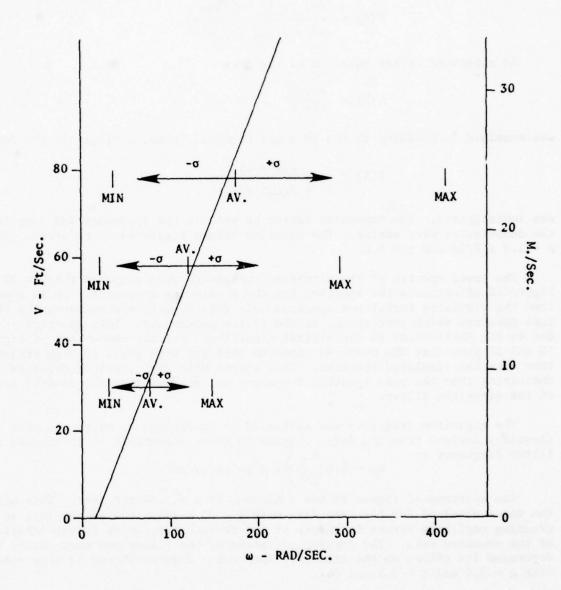


Figure 11 - Peak Spectral Frequency Versus Airspeed

The turbulence model was next examined to see how the properties of the simulated turbulence compared with the measured turbulence. The algorithm filter parameters were varied to determine if an improved match could be obtained between the simulated and test data turbulence. The basic filter equation proposed by reference (d) is

$$F(S) = \frac{\delta(x, y, z) \cdot \sqrt{4\zeta \omega_n^3}}{S^2 + 2\zeta \omega_n S + \omega_n^2}$$

An alternate filter equation of the form

$$F(S) = \frac{\delta \cdot / \sqrt{\omega}}{S + \omega}$$

was examined in addition to the original formula. Also, a filter of the form

$$F(S) = \frac{K(S + a)}{S^2 + 2\zeta\omega_n S + \omega_n^2}$$

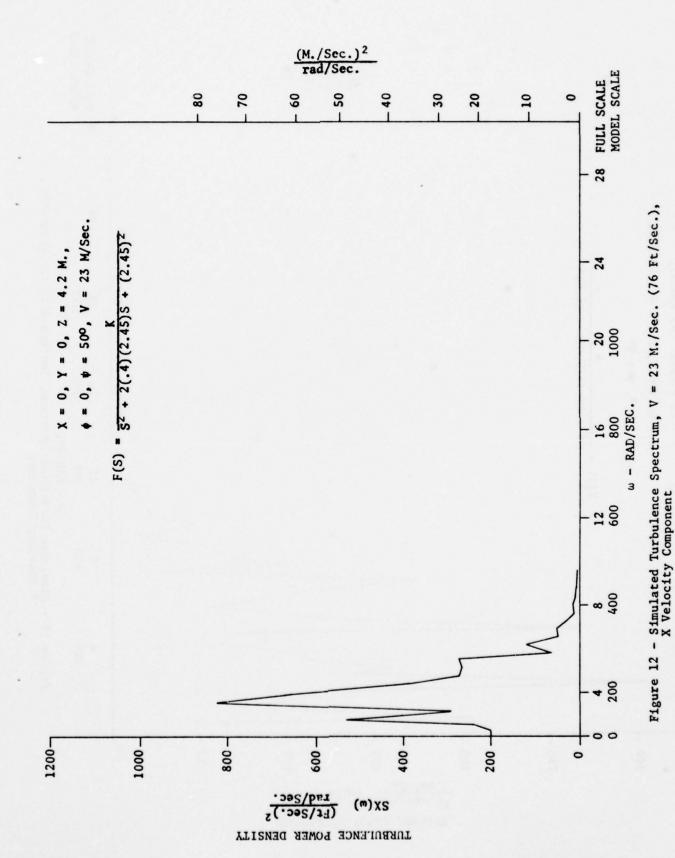
was investigated. The numerator factor as well as the frequency and damping of the denominator were varied. The baseline values suggested in reference (d) were $\omega = 1.9 \times V/59$ and $\zeta = 0.4$.

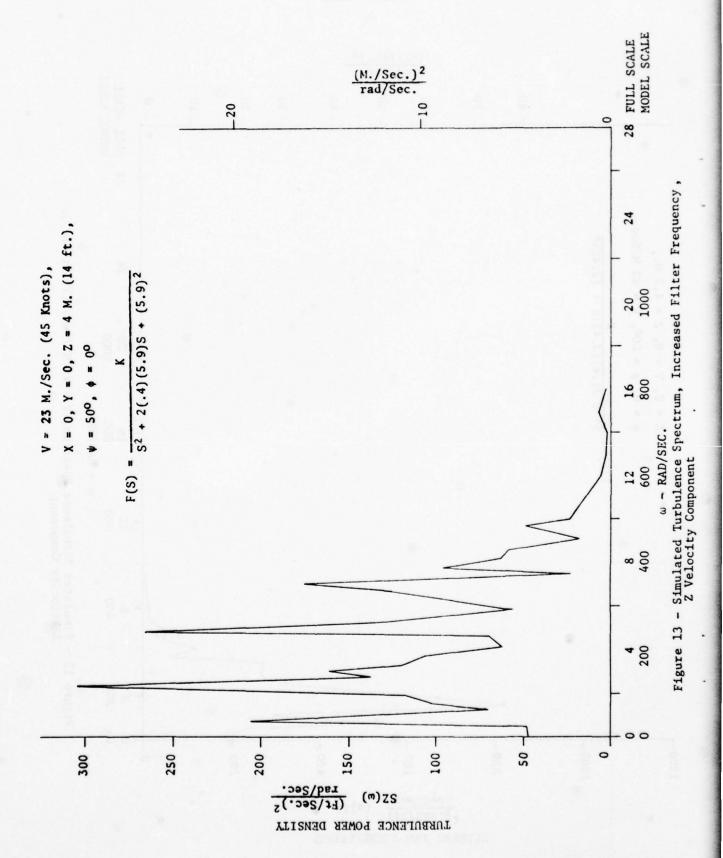
The power spectra of the simulated turbulence were computed for V = 23 M./S. Figure 12 illustrates the spectrum for the X velocity component. It is apparent that the simulated turbulence spectrum only very roughly approximates the theoretical spectrum which corresponds to the filter parameters. This apparently occurs due to the limitations of the digital algorithm. Further comparison of figures 10 and 12 show that the measured spectra contains more power at high frequencies than does the simulated spectrum. This agreed with the previous analysis indicating that the peak spectral frequency was greater than the natural frequency of the algorithm filter.

The algorithm frequency was increased in an attempt to match the peak frequency derived from the data. Figure 13 shows the effect of increasing the filter frequency to $\omega_Z = 4.6 \left(\frac{V}{59} \right) = 5.93 \text{ rad./sec.}$

The spectrum of figure 13 has a maximum at ω = 2.36 rad./sec. This matches the value obtained for the test data with V = 23 M./S. It also displays an increasing amplitude versus frequency at low frequencies, which is characteristic of the measured data. The damping parameter of the filter was next varied to determine its effect on the simulated spectrum. Figures 14 and 15 show spectra with ω = 5.9 and ζ = 0.1 and 0.7.

Compared to the case with ζ = .4, the configuration with ζ = 0.7 had its peak amplitude at a lower frequency and lower amplitude at high frequencies. The ζ = 0.1 case showed a large peak amplitude near the damped natural frequency and a rapid amplitude roll off at lower and higher frequencies. Thus, neither configuration appears to improve the correspondence with test data over that achieved with the original value of ζ = 0.4.





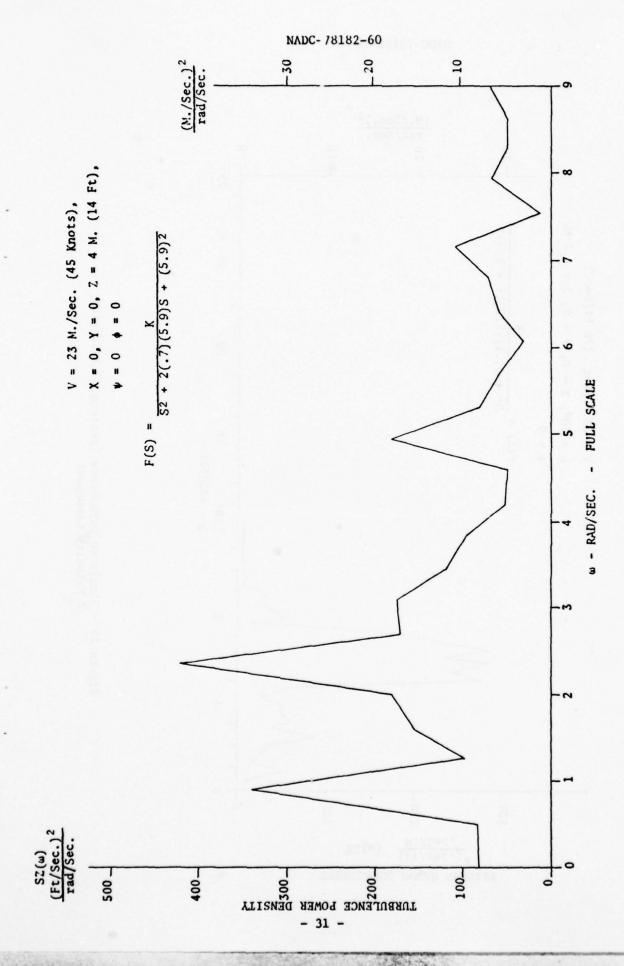


Figure 14 - Simulated Turbulence, 0.7 Damping, Z Velocity Component

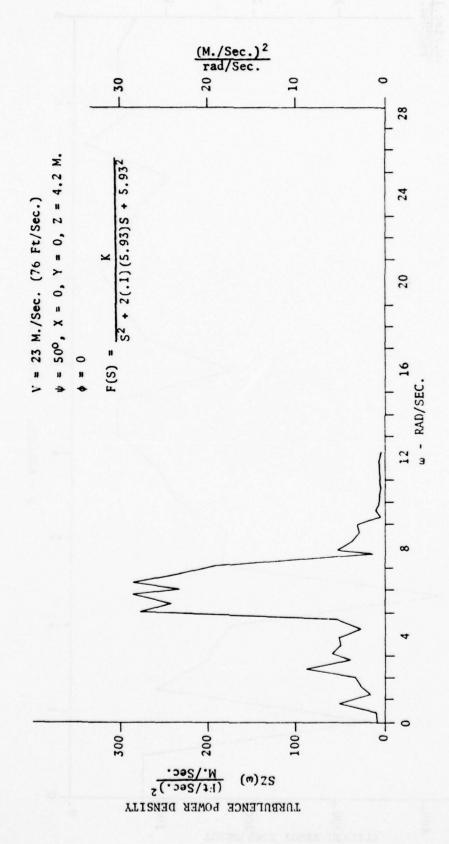


Figure 15 - Simulated Turbulence Spectrum, 0.1 Damping, Z Velocity Component

One additional filter configuration was examined in which a first-order numerator term was introduced with a break point at the denominator natural frequency. The resultant filter had the form

$$F(S) = \frac{K (S + \omega)}{S^2 + 2 (0.4) \omega S + \omega^2}$$

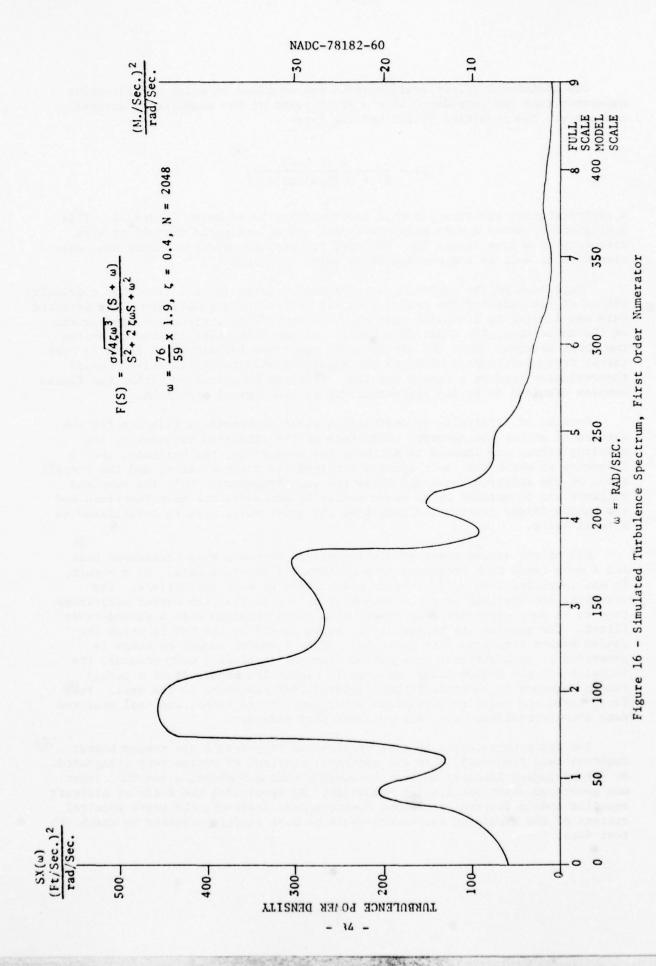
A representative spectrum for this configuration is shown on figure 16. This configuration shows a more pronounced peak and a less rapid dropoff at high frequency than does figure 12. However, it does not appear to match the measured data as well as the configuration shown on figure 13.

Comparison of the various power spectra is found to be a less than conclusive method of establishing the proper form for a turbulence simulation. The measured data was limited to 256 point samples. Because of the extremely random nature of the turbulence, the short data sample appears inadequate to exactly define the power spectra. Even the artificially generated turbulence is found to have rather irregular spectra although the equations used in the algorithm should theoretically produce a smooth spectra. This may be caused by either the finite samples examined or by the approximations of the digital algorithm.

Because of difficulty in defining an exact mathematical relation for the spectra of either the measured turbulence or the simulated turbulence, the modeling effort was limited to matching the mean value, the variance, the frequency at which the power spectra attained its maximum value, and the overall slope of the spectrum above and below the peak frequency. Only the mean and variance can be matched in an exact manner by adjusting the mean functions and the random filter gains. The remaining characteristics must be established on a trial basis.

All of the second-order simulation models showed a more pronounced peak and a more rapid high frequency dropoff than did the test data. As a result, it was concluded that a first-order model might be more appropriate. The principal disadvantage of the first-order filter is that the output velocities tend to be more jerky and less smooth than those produced with a second-order filter. The problem was recognized as being caused by the way in which the random number sequences were generated. When a random number sequence is generated at each aircraft integration interval (typically 0.05 second), the bandwidth of the random noise sequence is high. The magnitude of a purely random sequence is essentially uncorrelated from one point to the next. In fact, turbulent velocity variations occur over finite times, and real measured data shows correlation over a very short time duration.

The apparent solution to this problem was to generate the random number sequence less frequently than the aircraft equations of motion were integrated. By interpolating linearly between succeeding random numbers, a smoothed input was generated which had limited bandwidth. By specifying the ratio of aircraft equation update interval to random number update interval, the power spectral content of the simulated turbulence could be more readily adjusted to match the test data.



The smoothed random number sequence can be further processed to yield a reasonable simulation of the measured turbulence data by passing the number sequence through a properly designed first-order filter.

Because of the erratic nature of the measured data, it was decided to examine groups of points at various downstream ranges. Individual power spectra were normalized by dividing by their peak amplitudes. Then, these spectra were averaged on a component by component basis. The data selected included all cases for which $\phi = 0$, $\psi = 50$ deg, V = 23 M./Sec. The same process was performed for all data for which $\phi = 0$, $\psi = 50$ deg., and V = 9 M./Sec.

All points at a given downstream range were lumped together regardless of lateral position or height. Figures 17 to 20 show the effects of downstream station and freestream velocity on the character of the normalized spectra for the X, Y, and Z velocity components.

All four figures show a more pronounced dropoff of spectral amplitude with frequency for the X component than for the Y or Z components. Further, figures 17 and 18 show an overall lower frequency break point than do figures 19 and 20. This illustrates the fact that the turbulence frequency decreases as the distance downstream from the ship increases.

A least square straight line curve fit was first applied to the averaged test spectra. Then the break frequency of the first-order filter was assigned a value corresponding to the point at which the straight line reached a value of 0.5 times its value at zero frequency. This was chosen because the magnitude of

$$\left| \frac{1}{\frac{S}{\omega} + 1} \right|^2$$

reaches 0.5 at S = ω . The curve fit analysis was applied to the cases for V = 23 M./Sec. (76 ft/Sec.).

Based on the assumption that Strouhal scaling could be applied, the filter frequency was made proportional to freestream velocity. The selected frequency was ratioed to the value obtained for the V = 23 M./S case by multiplying by V/76. The selected turbulence algorithm was then run repeatedly to obtain a good estimate of the spectral properties of the model. These spectra were averaged component by component and compared with the test spectra.

The filter break frequencies selected for V = 23 M./S., and X = 0 were as follows:

TABLE V Filter Break Frequencies at X = 0

Component	Break Frequency	(rad./sec.)
x	8.17	
Y	10.41	
Z	10.0	

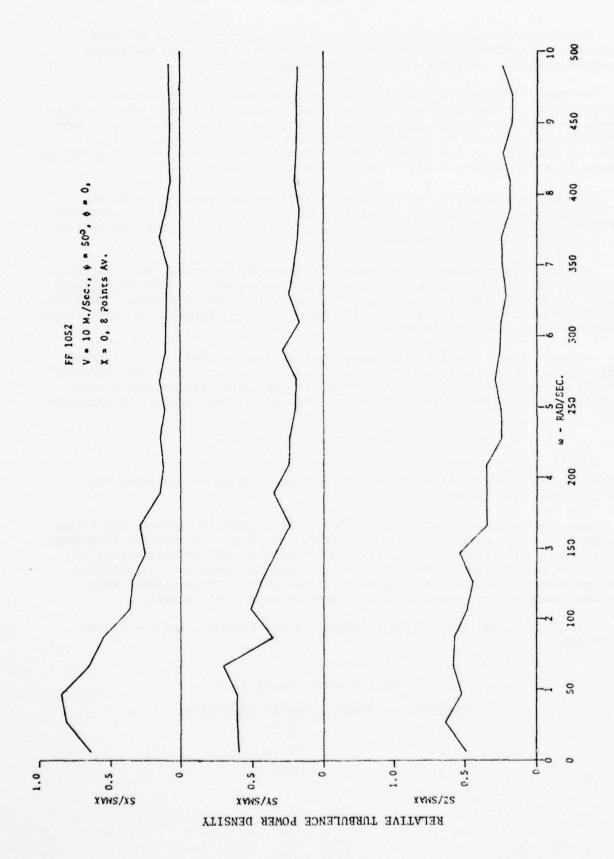


Figure 17 - Normalized Spectra for V = 10 M./Sec., X = 0 (Measured), X, Y, and Z Components

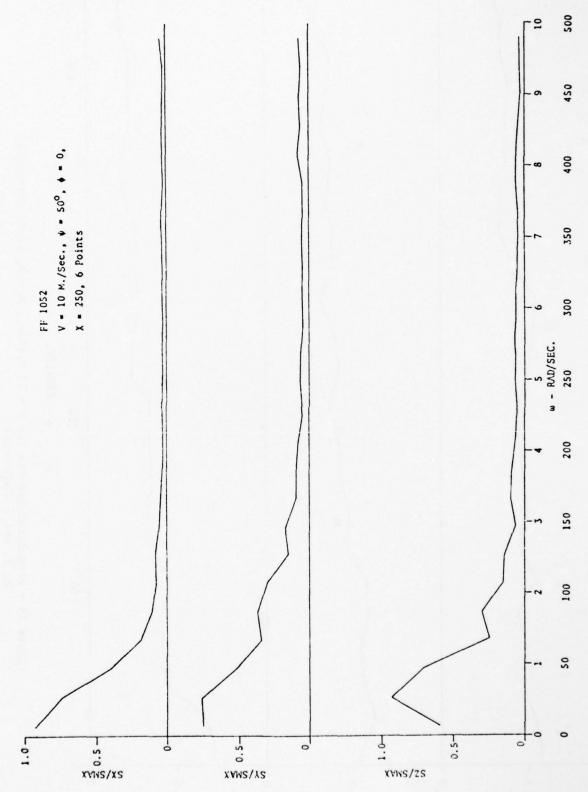
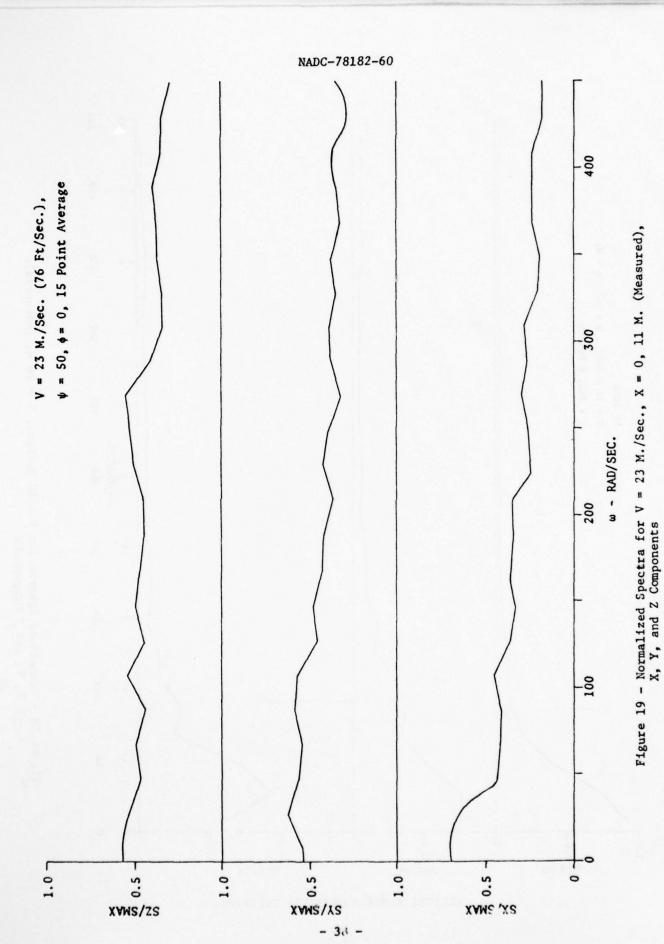
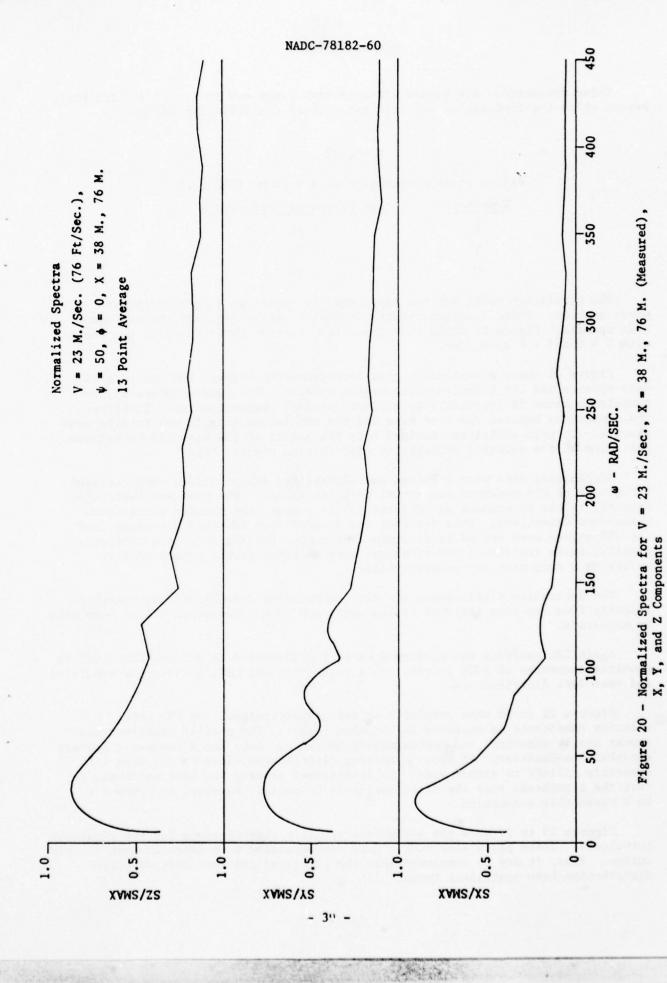


Figure 18 - Normalized Spectra for V=10~M./Sec.,~X=76~M. (Measured), X, Y, and Z Components

RELATIVE TURBULENCE POWER DENSITY





These frequencies are varied linearly with range out to X = 58 M. (190 ft.), beyond which the frequencies are held constant at the following values:

TABLE VI

Filter Break Frequencies at X = 58 M. (190 ft.)

Component	Break Frequency (rad./sec.)
x	1.58
Y	3.0
Z	2.88

The simulation model was run repeatedly to establish a representative power spectra. These averaged spectra were then plotted against the averaged test spectra. Figure 21 shows this comparison for the three velocity components with X = 0 and V = 23 M./Sec.

Figure 21 shows a reasonably good correspondence between the scaled test data spectra and the turbulence simulation spectra. The random nature of the turbulence makes it impossible to achieve an exact spectral match. Therefore, the comparison between the test data and the simulation data is not totally conclusive. To gain additional insight into the nature of the measured turbulence, the shape of the velocity probability distribution was examined.

Sample test data were selected and probability distributions were computed for groups of 256 measured sequential velocity values. The mean was subtracted from all values to produce an unbiased sample. Next, the maximum and minimum value were determined. This interval was divided into 20 equal divisions, and the 256 values were sorted to determine the number falling into each interval. Finally, these individual distributions were averaged over a number of test points on a component by component basis.

The derivative distribution was also computed by determining the change in velocity from one time interval to the next, and by sorting these values according to magnitude.

A similar analysis was performed using the simulated turbulence algorithm to generate sequences of 1024 points, and a comparison was made between the simulated and test data distributions.

Figures 22 to 24 show composite velocity distributions for the three velocity components as measured in the wind tunnel. The plotted distributions appear nearly symmetric and approximately Gaussian. Only the X component appears somewhat non-Gaussian. It shows a uniform distribution close to the mean with symmetric falloff to either side. No statistical testing has been performed to test the hypothesis that the distribution is Gaussian. However, it appears to be a reasonable assumption.

Figures 25 to 27 show the equivalent velocity distributions for the simulated turbulence. These plots also show a good approximation to a Gaussian type distribution. Thus, it may be concluded that the simulated and test data velocity distribution have equivalent forms.

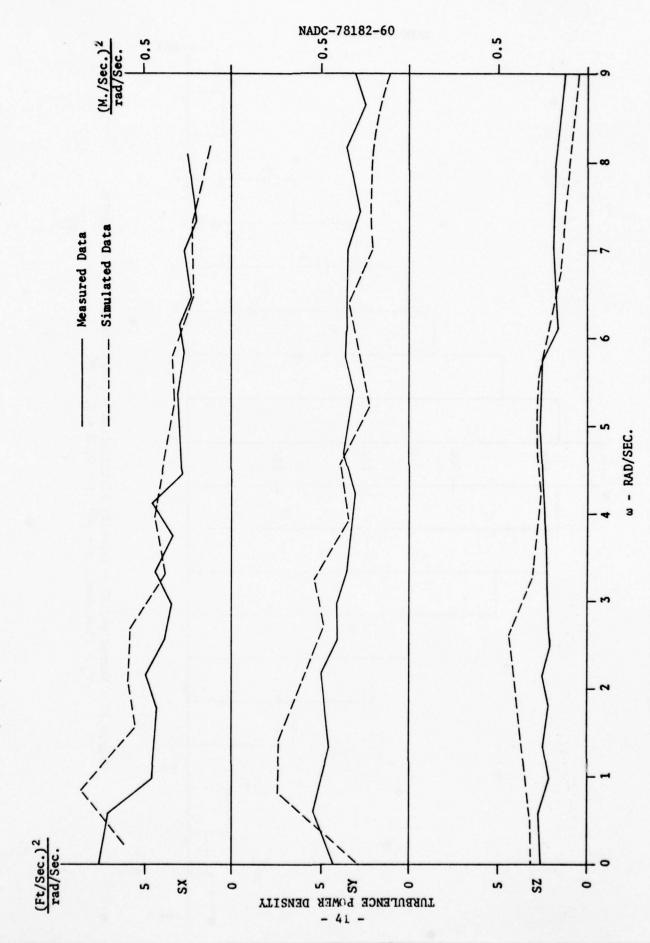


Figure 21 - Comparison of Test and Simulated Turbulence Spectra

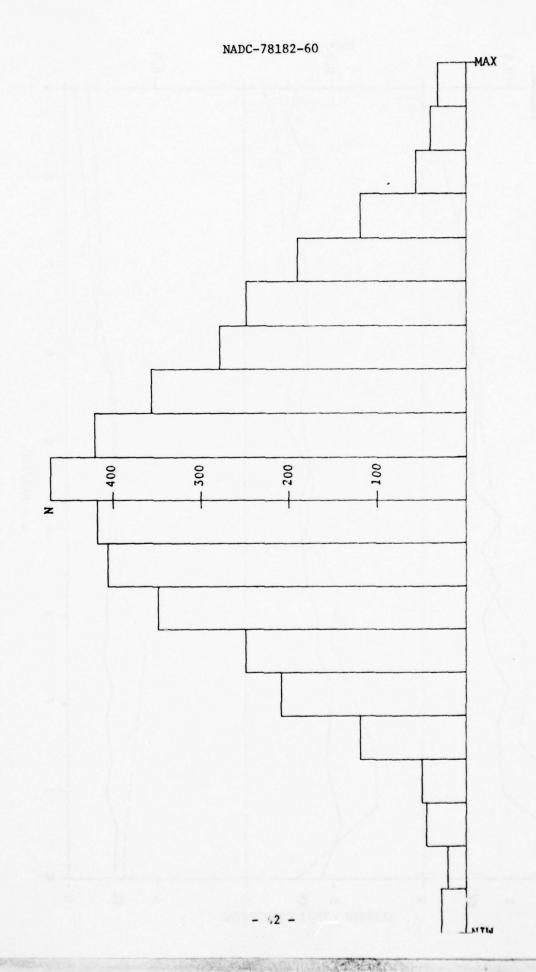


Figure 22 - Normalized VZ - Velocity Distribution - Composite of 16 Test Points, V = 23 M./Sec., ψ = 50°, ϕ = 0, X = 0, 27 M.

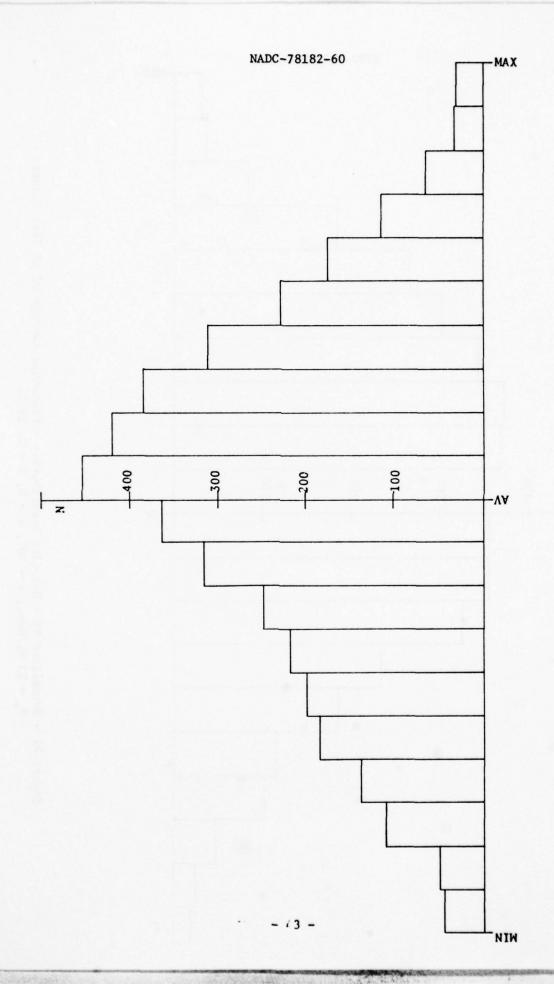


Figure 23 - Normalized VY - Velocity Distribution - Composite of 16 Test Points, V_{∞} = 23 M./Sec., ψ = 50°, ϕ = 0, X = 0, 27 M.

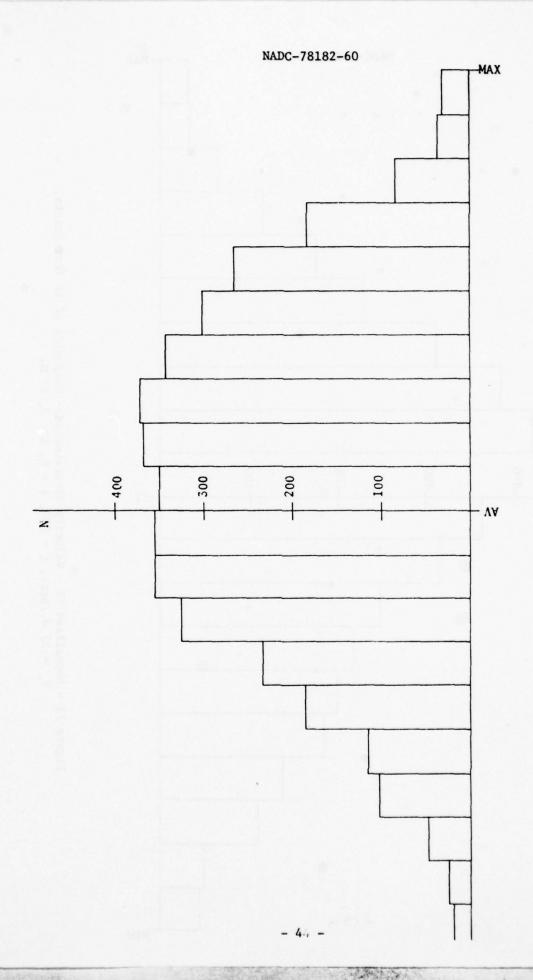


Figure 24 - Normalized VX - Velocity Distribution - Composite Average of 16 Test Points $V_{\infty}=23$ M./Sec., $\psi=50^{\circ}$, $\phi=0$, X = 0, 27 M.

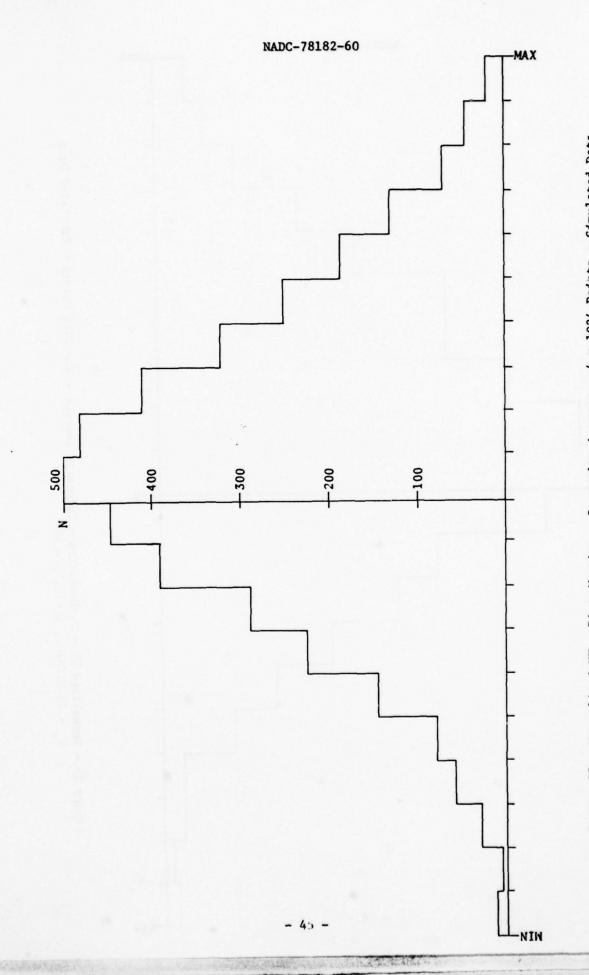


Figure 25 - Normalized VX - Distribution - Composite Average - 4 x 1024 Points - Simulated Data $V_{\infty} = 23 \text{ M./Sec.}, \phi = 0, \psi = 50^{\circ}$

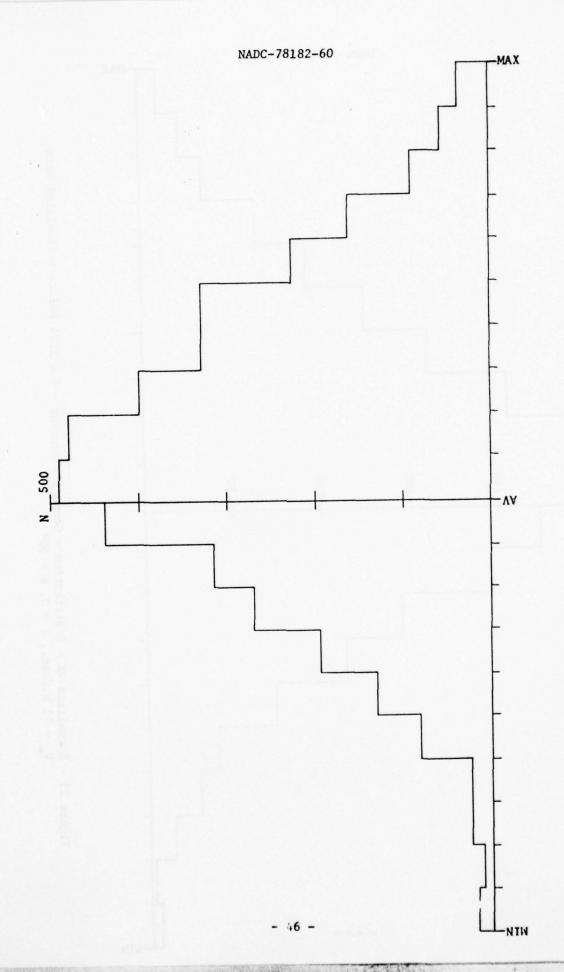
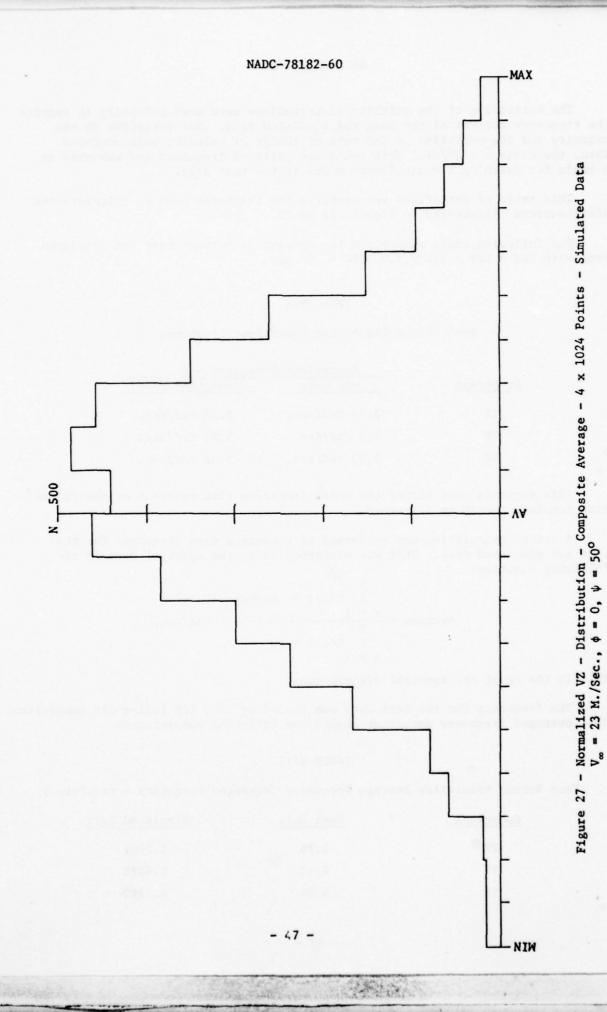


Figure 26 - Normalized VY - Distribution - Composite Average - 4 x 1024 Points - Simulated Data $V_{\infty}=23$ M./Sec., $\phi=0, \psi=50^{\circ}$



The derivative of the velocity distributions were used primarily to examine the frequency content of the test and simulated data. The variation in the velocity and the variation in the rate of change of velocity were computed. Then, the ratio $\bar{\omega}=\delta \hat{V}/\delta V$. This ratio has units of frequency and was used as a basis for matching the simulation model to the test data.

This ratio of variations was computed for the cases used to calculate the distributions illustrated in figures 22 to 27.

The following table summarizes the comparison between test and simulated data with RNX = RNY = RNZ = 5.0, DTW = .05 sec.

TABLE VII

Test Versus Simulation Equivalent Frequency

	Equivalent Frequency - $\bar{\omega}$		
Component	Test Data	Simulation Model	
vx	3.78 rad/sec.	5.38 rad/sec.	
VY	4.2 rad/sec.	5.29 rad/sec.	
VZ	4.23 rad/sec.	5.52 rad/sec.	

This suggests that either the model iteration time constant or the filter time constant should be increased.

A second calculation was performed to compute a mean frequency for the test and simulated data. This was performed using the spectral data in the following equation:

Average =
$$\frac{\sum_{\Sigma} S(\omega)i * \Delta\omega * \omega i}{\sum_{\Sigma} S(\omega)i * \Delta\omega} - rad/sec.$$

$$i = 1$$

This is the cg of the spectral distribution.

The frequency for the test data was scaled by 1/50 for full-scale comparison. This averaged frequency parameter showed the following comparisons:

TABLE VIII

Test Versus Simulation Average Frequency (Averaged Frequency - rad./sec.)

Component	Test Data	Simulated Data
vx	3.76	4.7707
VY	4.44	4.4115
VZ	4.54	4.7282

The fact that the equivalent frequency of all three components of the simulated turbulence is nearly identical in spite of differences in the filter constants suggests that the random number calling interval dominates the spectral distribution of the simulated turbulence. Therefore, the program scale factors RNX, RNY, and RNZ were adjusted from initial values of 5.0 to RNX = 7.12, RNY = 6.3, and RNZ = 6.52 based on the ratios of the equivalent frequency parameter. For these parameters, the equivalent and average frequencies compare as follows:

TABLE IX

Test Versus Adjusted Simulation Frequency

Test		Simulation		
Component	ω	ωΑν	_ω_	ωΑν
vx	3.78	3.76	4.51	3.64
VY	4.2	4.44	4.63	3.68
VZ	4.23	4.54	4.65	3.79

Given the accuracy of the analysis and the limited sample size examined, this appears to represent a near optimum match. Figure 28 illustrates the resulting spectra for a single simulation run.

CORRELATION ANALYSIS

Certain test data points were selected for correlation analysis. The autocorrelation and cross-correlation functions were computed to determine if the gusts were purely random or if any time or space correlation existed. The equation used was

$$R_{XY}(N) = \frac{\sum_{i=N}^{M} \frac{(vx_i - \overline{vx}) \cdot (vy_{i-N} - \overline{vy})}{(M-N)}}{\left(\sum_{i=N}^{M} \frac{(vx - \overline{vx})(vx - \overline{vx})}{M}\right) \cdot \left(\sum_{i=1}^{M} \frac{(vy - \overline{vy})(vy - \overline{vy})}{M}\right)}$$

As expected, the autocorrelation functions were found to have unit values for zero time shift, but were close to zero for all non-zero time shift values. This means that no significant periodicity exists in the measured data. Most of the crosscorrelation functions were found to be essentially zero for all time shift values. The condition examined was X=0, Y=0, $\psi=50^{\circ}$, $\phi=0^{\circ}$, H=4.2, 7.6 M. There was no space correlation between velocities at H=4.2 M. and H=7.6 M. above deck.

The only significant crosscorrelation uncovered was between the X and Y components at H = 4.2 M. (14 ft.) This can be interpreted as a vorticity in the wind velocity about the Z axis at this point. This corresponds to an aircraft

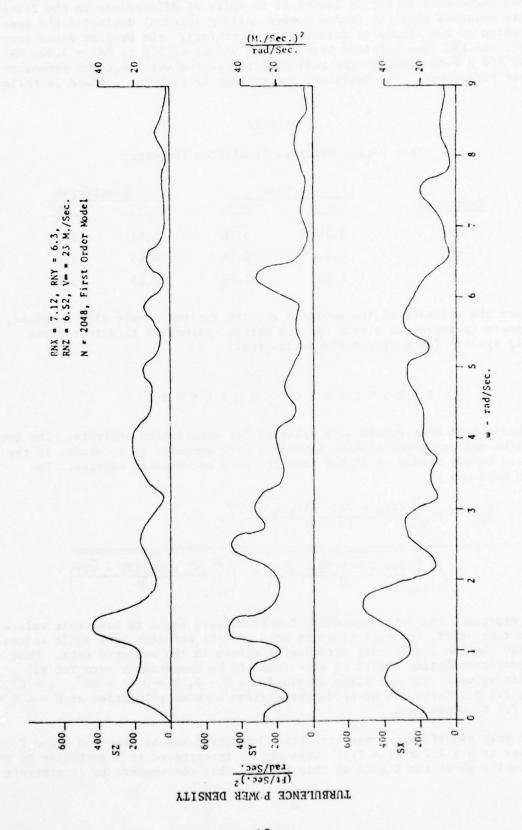


Figure 28 - Simulated Spectra With Adjusted Time Constants, X, Y, Z Components

TABLE X

Correlation Summary of Test Data $V_{\infty} = 23$ M./S., $\psi = 50^{\circ}$, $\phi = 0$

Point 1: X = 0, Y = 0, Z = 4.2 M.

Point 2: X = 0, Y = 0, Z = 7.6 M.

 $\Delta T = 0.0061$ second model scale

= 0.31 second full scale

Compo	nents	ΔT-Shift 0	_1_	2
x_1	x_1	1.0	0.288	-0.057
Y ₁	Y ₁	1.0	-0.08	-0.1
z_1	z_1	1.0	0.064	-0.014
x_1	Y ₁	-0.544	-0.154	0.094
Y ₁	z_1	-0.05	-0.05	0.08
x_1	z_1	-0.1	0.04	0.018
x_2	X ₂	1.0	0.24	-0.01
Y ₂	Y ₂	1.0	-0.08	-0.002
z_2	z_2	0.998	-0.058	-0.206
x_2	Y ₂	-0.303	-0.129	0.0409
Y2	z_2	0.0974	-0.081	-0.095
$\mathbf{x_1}$	Z ₂	-0.1	-0.001	0.08
x_1	X ₂	0.237	0.16	-0.074
\mathbf{y}_1	Y ₂	0.284	0.0107	-0.074
z_1	z_2	0.143	0.0446	0.0455
$\mathbf{x_1}$	Y ₂	-0.15	-0.076	-0.076
\mathbf{Y}_{1}	z_2	0.075	-0.174	-0.0216
x_1	z_2	-0.096	0.121	0.171

yaw rate. It is not clear whether this has a significant effect on aircraft motion so that provision for including this effect should be added to the model. The effect does not appear strong enough to justify additional complexity in the model.

Evaluation of the test data and the various model algorithms do not lead to an exact and definite conclusion regarding the values of the model parameters.

A question arises as to whether the exact turbulence spectrum must be duplicated by the model in order to yield a useful analytical tool. In an attempt to answer this question, the closed-loop pitch response to horizontal gusts was computed using the original second-order model format. RMS pitch response was computed for a range of spectral gust frequency model parameters. A closed-loop pitch transfer function was calculated for a representative VSTOL (AV8A) at a 62 M./S. (120 knot) transition condition. The pitch loop was closed with a simple gain pitch SAS and pilot model incorporating pitch attitude and pitch rate feedback through a delay.

The closed-loop pitch to horizontal gust transfer function was calculated and the RMS gust response was then determined using the equation:

$$\delta\theta^2 = \frac{1}{2\pi} \int_{-\infty}^{\infty} \left| \frac{N \text{ ug}}{D'} \right|^2 \phi_{\text{ugust}}^{\text{(jw)}} \cdot \text{dw}$$

where $\frac{N\ ug}{D'}$ is the closed-loop transfer function and ϕ_{ugust} is the gust power spectrum.

The gust power spectrum is developed by squaring the magnitude of the gust transfer function as follows

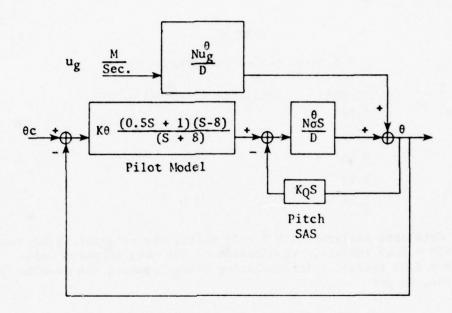
$$\frac{\text{Gust Velocity}}{\text{Random Input}}(S) = \frac{\delta \cdot 2 \cdot \sqrt{\zeta \omega^3}}{S^2 + 2\zeta\omega + \omega^2}$$

$$\Phi_{\text{gust}}(S) = \frac{\delta^2 4 \zeta \omega^3}{(S^2 + 2\zeta \omega S + \omega^2)(S^2 - 2\zeta \omega S + \omega^2)}$$

The system block diagram is illustrated by figure 29.

The closed-loop gust transfer function then becomes

$$\frac{\theta}{ug}(S) = \frac{(3.28)(S+8)(-0.002832S^2 + 0.0005604S + 0.0003527)}{(S^5 + 7.046S^4 + 17.9199S^3 + 27.827S^2 + 16.692S + 2.8202)}$$



$$N_{0}^{\theta}S = -8.057 S^{2} - 5.218 S - .823 Rad./rad.$$

$$D = S^{4} + 0.7382 S^{3} - 0.9896 S^{2} - 0.2859 S + 0.006864$$

$$N_{0}^{\theta} = 3.28 X \left(-0.002832 S^{2} + 0.0005604 S + 0.0003527\right) \frac{Rad}{M./Sec}.$$

$$K^{\theta} = 0.42 \text{ rad/rad}.$$

 $K_Q = -0.49 \text{ rad/rad/sec.}$

Figure 29 - Closed-Loop Gust Response Transfer Function

RMS gust responses were calculated for the following parameters

 $\sigma_{\rm ug}$ = 7.1 M./S. (23.3 ft/sec.), ζ = 0.4, ω = 1.4, 2, 3, 5, and 7 rad/sec.

The results follow:

TABLE XI
RMS Pitch Versus Gust Frequency

$\sigma\theta$ - deg.	Cust Frequency - rad./sec.
3.16	1.4
2.95	2.0
2.43	3.0
1.76	5.0
1.44	7.0

For the data case analyzed with V = 23 M./S., the original model uses $\omega_{\rm X}$ = 1.9 x V/59 = 2.45 rad/sec. Examination of the data suggests using $\omega_{\rm X}$ = 3 x V/18 = 3.86 rad/sec. Interpolating linearly among the results from the sample case, we get

$\sigma\theta$ - deg.	ω - rad./sec.	
2.72	2.45	
2.14	3.86	

This corresponds to a 21-percent difference in sigma values for a 64-percent variation in frequency.

Thus, the frequency of the gust model does significantly affect the aircraft response for constant RMS gusts. However, a gust model which predicts gust response to within 10 percent would probably be a satisfactory tool. Thus, the assumed filter algorithm is not extremely critical. The sensitivity shown by the sample indicate that it would be sufficient to define the frequency parameter to within 25 percent of its true value. In contrast, the aircraft response varies directly with RMS gust amplitude. Thus, it is most important to accurately match the gust RMS amplitude.

TIME HISTORY COMPARISON

One final comparison of the simulated and measured turbulence was made by plotting the velocity time histories of the three velocity components. The case selected was

$$X = 0$$
 $V_{\infty} = 23 \text{ M./s.}$
 $Y = 0$ $\psi = 50^{\circ}$
 $Z = 4.2 \text{ M.}$ $\phi = 0$

The experimental data was recorded at a time interval of 0.0061 second. This value was scaled up by a factor of 50 to yield a plot scale interval of 0.31 second. Simulated data points were calculated at a 0.05-second time interval. Because of the measurement interval, the bandwidth of the experimental data was limited to 10.13 rad./sec. Thus, higher frequency oscillations might have been present, but they could not be detected.

The simulated and test velocity sequences were compared on the basis of maximum, minimum, mean, and variance values as well as a qualitative comparison of the shapes of the plotted sequences. Figures 30 to 32 illustrate the relationships for the three velocity components. The mean and variance values compare well for all three components. The maximum and minimum values seem consistent in all cases with the magnitudes of the mean and variances.

A qualitative comparison of the number of local maxima and minima in a 10-second period show that the frequency content of the simulated and measured velocities compare satisfactorily.

RESULTS AND CONCLUSIONS

The CVA turbulence model contained herein remains basically unchanged from the version described in reference (c) as a result of analysis performed for this study. It is suitable for simulation of aft approaches and forward takeoffs of conventional and VSTOL aircraft.

The FF 1052 turbulence model is designed to permit VSTOL takeoff and landings from any angle. Wind conditions are currently limited to relative wind angles of 0, 30, and 50 degrees at total velocities of 10, 18, and 23 M./S. (20, 35, and 45 knots).

After considerable iteration, the FF1052 turbulence model structure was fixed with these features:

- 1. Exponential and linear extrapolation of tabulated mean and variance velocity values beyond the region of measured data.
- 2. First-order exponential filtering of random number inputs using inverse time constants that decrease linearly with range downstream.
- 3. The random number subroutine used to generate the three gust velocities are called less frequently than the basic simulation loop time, and the resultant random number sequences are linearly interpolated.
- 4. The random number update interval is selected to match test data spectral distributions.
 - 5. The filter time constants vary inversely with freestream steady velocity.
- 6. The frequency content of the three velocity components display different characteristics with the horizontal component having a lower frequency spectrum than the Y and Z components.

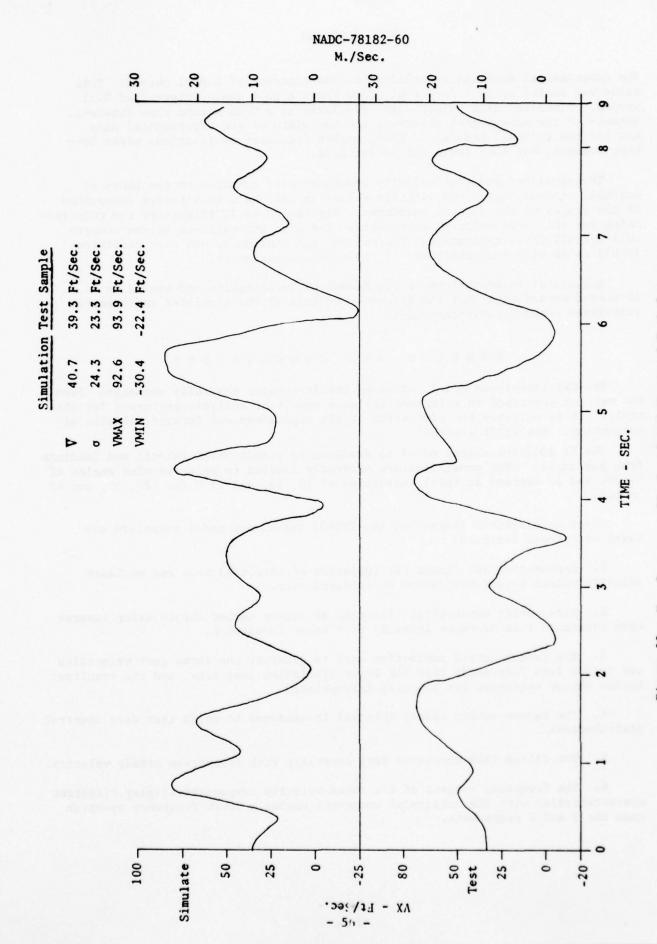
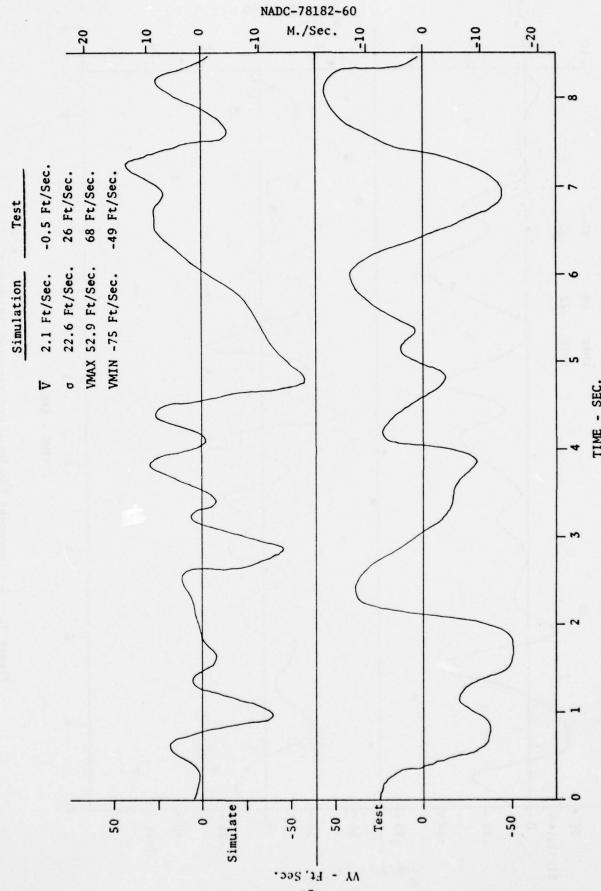


Figure 30 - X - Component Simulated and Measured Turbulence



TIME - SEC. Figure 31 - Y - Component Simulated and Measured Turbulence

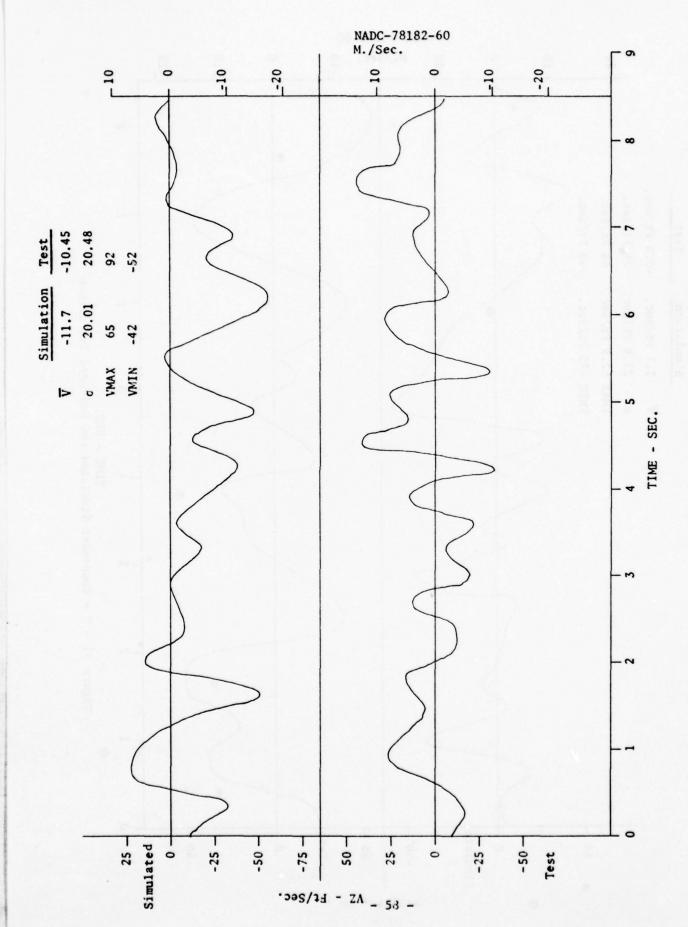


Figure 32 - Z - Component Simulated and Measured Turbulence

- 7. Although some cross-correlation between velocity components was observed in the measured data, it does not appear significant enough to include in the simulation model.
- 8. For 45-knot wind and the aircraft located over the deck, the filter frequency parameters were selected with the following values:

Component	Frequency - rad./sec.	
X	8.17	
Y	10.41	
Z	10.00	

9. These frequencies decrease linearly to X = 58 M. (190 ft.) where the filter frequencies become

Component	Frequency - rad./sec.
X	1.58
Y	3.0
Z	2.88

10. The test simulation was set up to update wind velocity intervals at 0.05 second intervals. The random number sequences were updated at the following multiple interval size:

Component	Update	Interval - Sec.
x	0.05	x 7.12 = 0.356
Y	0.05	x 6.3 = 0.315
Z	0.05	x 6.52 = 0.326

- 11. Examination of the experimental data shows that the turbulence velocities reasonably approximated a Gaussian distribution. However, the distributions show some flattening and less peaking around the mean than do ideal theoretical distributions.
- 12. Analysis indicates that it is more important to exactly match the mean and variance of the turbulence velocities than to exactly match the spectral shape.

RECOMMENDATIONS

Because of differences in digital computers and particularly in random number generator subroutines, prospective users of these computer subroutines should follow the following precautions:

- 1. Run the model repeatedly for at least 100 seconds of simulation time at a fixed location in space.
- 2. Compare the mean and variance of the simulated data with that of the input tables corresponding to the selected point.
- 3. Compute the Fourier transform of the simulated turbulence and compare these with the spectral plots contained in this report.
- 4. Adjust the filter gains, time constants, and number update ratios RNX, RNY, RNZ if necessary.
- 5. The FF 1052 model should be tested on a moving base piloted simulation to get pilot confirmation of its validity.

LIST OF SYMBOLS

CVA	Attack Aircraft Carrier
PSIS	Ship Heading - Rad.
PSIREL	Wind Over Deck Relative Angle - Rad.
Rxy	Cross Correlation Function
S	Laplace Operator - 1/Sec.
Sx, y, z	Power Spectral Density
STO	Short Take Off
u	Longitudinal Wind Velocity - M./Sec.
ug	Longitudinal Gust Velocity - M./Sec.
V	Lateral Wind Velocity - M./Sec.
VG	Lateral Gust Velocity - M./Sec.
νο	Trim Aircraft Velocity - M./Sec.
VEWBIC	East Component of Natural Wind - M./Sec.
VNWBIC	North Component of Natural Wind - M./Sec.
VW	Total Wind Over Deck - M./Sec.
vs	Ship Speed - M./Sec.
vx	X Component of Wind Velocity - M./Sec.
VY	Y Component of Wind Velocity - M./Sec.
VZ	Z Component of Wind Velocity - M./Sec.
V _∞	Free Stream Wind Velocity - M./Sec.
W	Lateral Wind Velocity - M./Sec.
х	Aircraft Position Aft of Ship - M.
Y	Aircraft Position Left or Right of Ship Centerline - M.
Z	Aircraft Altitude Above Touchdown Point - M.
α	Aircraft Angle of Attack - Deg.
Δu VS	Normalized Horizontal Velocity Increment
Δw VS	Normalized Down Wash Velocity Increment
θ	Aircraft Pitch Attitude - Deg.
σ	Root - Mean Squared Value
τ	Gust Time Constant - Sec.
ф	Ship Roll Angle - Deg.

$\Phi_{Vo}^{\underline{\Delta u}}$	Horizontal Gust Power Spectrum - (ft/sec.) ² /(rad/sec.)
$\Phi_{\overline{Vo}}^{\underline{\Delta v}}$	Lateral Gust Power Spectrum - (ft/sec.) ² /(rad/sec.)
$\Phi_{\overline{Vo}}^{\underline{\Delta w}}$	Vertical Gust Power Spectrum - (ft/sec.)2/(rad/sec.)
ψ	Ship Heading Angle - Deg.

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APPENDIX A

Listing of CVA Turbulence Model

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If (1057-E0.1) UBT=0. If (17487-E0.1) WUT=0. NG=201119-WG.211119-WD.4 NG=20112-WG.211119-WD.4 NG=2012-WG.211119-WD.4 NG=202-WG.4-712-WD.4 NG=202-WG.4-712-WD.5 VG=202-WG.4-712-WD.5 VG=702-WG.4-712-WD.5 VG=702-WG.4-712-WD.5 VG=702-WG.4-712-WD.5 VG=702-WG.4-712-WD.5 VG=702-WG.4-712-WD.5 VG=801-WG.4-712-WD.5 VG=901-WG.4-712-WD.5 VG=001-WG.6-0-1 VG=00 VG=000 VG	
IF (IVET *EC*1) *VUT=0. We=Z01110*K6.211110*KD3 HW = Z0112*W6.211110*KD3 HW = Z0112*W6.211110*KD4 RU = Z012*W6.21112*RD4 RU = Z010*W6.2112*RD4 WG = Z(12*W6.2712*RD5) VG = Z(2*W6.2712*RD5) VG = Z(2*W6.2712*RD5) VG = Z(2*W6.2712*RD5) VG = Z(2*W6.2712*RD5) VG = Z(1-W6.2712*RD5) VG = Z(1-W6.2712*RD5) VG = VG + VG 2 + VG 3 + VG 4 IF (ILTURB * EQ -1) GO TO 5 CONTINUE UTURB = URT * VG WTURB = WRT * VG WTURB * VG WTUR	
IF (IABT.EU.1) WBT=0. WG=Z0111=WG.Z1111=WD3 RO3=RU(3) GR(3) UG=Z0112=UG.Z1112=RD4 RO4=RO(4) GR(4) VG3=ZU2=VG2-Z13=WD5P VG3=ZU1-VG3-Z13=WD5P VG4=ZC2-VG4-Z14=RD5P VG4=ZC2-VG4-Z14=RD5P VG=VG1-VG2-VG3-Z14=RD5P VG=VG1-VG2-VG3-Z14=RD5P VG=VG1-VG2-VG3-Z14=RD5P VG=VG1-VG2-VG3-Z14=RD5P VG=VG1-VG2-VG3-Z14=RD5P VG=VG1-VG2-VG3-Z14=RD5P VG=VG1-VG2-VG3-VG4 I (ILTURB-RD1-VG3-VG3-VG4 VG=0.	
# # # # # # # # # # # # # # # # # # #	
##G=Z0111=##D3 ##G=Z0111=##G+Z1111=##D3 ##G=Z012=##G+Z1112=##D4 ##G=Z012=##G+Z1112=##D5 ##G=Z012=##G+Z112=##D5 ##G=Z012=##G+Z113=##D5P ##G=Z012=##G+Z013=##D5P ##G=Z012=##G+Z013=##D5P ##G=Z012=##G+Z013=##D5P ##G=Z012=##G+Z013=##G+Z013=##G+Z013=##G-Z013=###G-Z013=###G-Z013=###G-Z013=##G-Z013=##G-Z013=##G-Z013=###G-Z013=###G-Z013=###G-Z0	
RO3=RU(3) GR(3) UG=Z011Z**UG**Z111Z**RD4 RO4=RO(4)*GR(4) VG1=Z02**VG2**Z112**RD5P VG3=Z02**VG2**Z13**RD5P VG4=Z0Z**VG4*Z14**RD5P VG4=Z0Z**VG4*Z14**RD5P VG=VG1**VG2**VG3**VG4 If (ILTURB**E0*1) GO TO 5 UG=0.0 VG=0.0 VG=0	
UG=Z0112*UG*Z1112*BD4 RO4=RD(4)*GR(4) VG1=Z01*VG1*Z11*BD5P VG3=ZU2*VG4*Z13*BD5P VG3=ZU2*VG4*Z13*BD5P VG4=ZC2*VG4*Z13*BD5P VG4=ZC2*VG4*Z13*BD5P VG5=ZU2*VG3*YG4 IF (ILLTURB*E0.1) GO TO 5 UG=0.0 VG=0.0 VG=0	
### ### ### ### ### ### ### ### ### ##	
VG1=2C1=VG1-Z11=RDSP VG3=ZC1=VG3-Z13*HDSP VG4=ZC2=VG4-Z14*RDSP VG4=ZC2=VG4-Z14*RDSP VG=VG1-VG2-VG3-VG4 IC (ILTURE.EQ.1) GO TO.5 VG=0.0	
VG1=Z01=VG1+Z11=HDSP VG2=Z02=VG4-Z13=ADSP VG4=ZC2=VG4-Z13=ADSP VG4=ZC2=VG4-Z13=ADSP VG4=ZC2=VG4-Z13=BDSP VG4=ZC2=VG3+VG4 IF (ILLTURB.EQ.1) GO TO 5 UGE 0.0 VG = 0.0 VG	
VG2=ZU2~VG2~7I2~RU5P VG3=ZU1~VG3.ZI3*RD5P VG47C2~VG4.ZI4*RD5P VG5+VG1~VG2~VG3+VG4 IF (ILTURB.EQ.1) GO TO 5 VG=0. VG	
V63=Z(1)+V63+Z13+H05P V64=ZC2+V64+Z14*R05P RD5P=R0(5)+RR(5) V6=V61+V62+V63+V64 If (ILTURB.E0.1) GO TO.5 UG=0.0 V6=0.0 V	
V64=762*V64.2I4*RU5P RD5p=40(5)*aR(5) V6=V61*V62*V63*V64 IF (ILTURB.E0.1) GO TO.5 UG=0.0 V6=0.0 V6=0.0 V6=0.0 V6=0.0 V6=0.0 VG=0.0 V	
### ### ### ### ### ### ### ### ### ##	
RD5P=40(5)*GR(5) VG=VG1+VG2+VG3+VG4 If (ILTURE.EQ.1) GO TO 5 UG=0.0 VG=0.0 VG=0.0 VTURB=WBT+VG	
VG=VG1+VG2+VG3+VG4 IF (ILTURB.EG.1) GO TO 5 UG=0. VG=0. VG=0. S CONTINUE UTURB=URT+UG VTURB=VBT+VG VTURB=VBT-VG VTURB-VG VTUR	
IF (ILTURB.EQ.1) GO TO.5 UG=0.0 VG=0.0 VG=0	
1F (ILTURBLEGAL) GO 10.5 UG=0.0 VG=0. VG=0. VG=0. VTURB=UBT+UG VTURB=WBT+VG WTURB=WBT+VG WTURB=WBT+VG VTU	
VG=0.0 VG=0. WG=0. CONTINUE UTURB=UBT+UG VTURB=WBT+UG VTURB=WBT+WG PR=RNI *RD (6) *GR (6) * (ZRI*ARS (XD) *ZRZ) VR=RNI *RD (7) *GR (7) * (YRI*ABS (XD) *YRZ) URIS=WHIS+URI VHIS=WHIS+URI URIS=WHIS+URI URIS=WHIS+URI	
VG=0. WG=0. UTURB=URT+UG VTURB=VBT+VG VTURB=VBT+VG VTURB=VBT+VG VTURB=VBT+VG VTURB=VBT+VG VTURB=VBT+VG VTURB=VBT+VG VTURB=VBT+VG VT=RN1*RD(5)*GR(5)*(ZR1*ABS(XD)*ZR2) VR=RN1*RD(5)*GR(7)*(YR1*ABS(XD)*YR2) UH1S=VH1S+VB1 UH2S=UH2S*UH2	
5 CONTINUE UTURB=URT+UG WTURB=WBT+WG WTURB=WBT+WG S=KN1=RD(G)=GR(G)=(ZR1=ARS(XD)+ZR2) YR=RN1=RD(G)=GR(G)=(ZR1=ARS(XD)+ZR2) UHIS=WHIS+URI UHIS=WHIS+URI UHSS=URIS+UHZ	
5 CONTINUE UTURB=UBT+UG VTURB=UBT+UG VTURB=WBT+WG ZR=KN1 *RD (6) *GR (6) * (ZR1*ARS (XD) +ZR2) YR=RN1 *RD (7) *GR (7) * (YR1*ABS (XD) +YR2) UR1S=UH1S+UR1 WH1S=WH1S+UR1 UR2S=UR2S+UR2	
5 CONTINUE UTURB=URT+UG VTURB=WBT+VG ATURB=WBT+VG ZP=RN 1 *RD (5) *GR(6) * (ZR1*ABS(XD) + ZR2) YR=RN 1 *RD (7) *GR(7) * (YR1*ABS(XD) + YR2) UHIS=WHIS+URI UHSS=UR2S+UH2	
UTURB=URT+UG WTURB=WBT+VG WTURB=WBT+VG ZR=RN1*RD(6)*GR(6)*(ZR1*ARS(XD)+ZRZ) YR=RN1*RD(7)*GR(7)*(YR1*ABS(XD)+YRZ) URIS=WHIS=WB1 URIS=WHIS+WB1 URIS=WHIS+WB1	
VIUNBENTING VIUNBENTING VIUNBENTING VIUNBENTING ZRENINGRO(6) 06R(6) 0(ZRIOAS(XD) + ZRZ) YRERNINGRO(7) 06R(7) 0 (YRIOABS(XD) + YRZ) URISERHISHUNI VHISERHISHUNI URISERHISHUNI	
V TURB = VB T + VG	
#TURB=#BT+#G	
78=RN1 +RD (6) + YR=RN1 + RD (7) +G URIS=URIS+URI WHIS=KRIS+WRI URYS=KRIS+WRI URYS=KRIS+WRI URYS=URSS+URI	
YR=RNJ 94D (7) 96 UHIS=UHIS+URI WHIS=KHIS+WRI UHYS=URZS+UHZ	
VERNITATO (7) 96 URISHITATO (7) 96 VERNITATO (7) 96 URISHITATO (7)	
UHIS=UHIS+UAI PHIS=XHIS+PBI UHYS=UHZS+UHZ	
MHS=WHIS+WB1 UR2S=UR2S+UH2	
2H1+27H1-27H1	
UR2S=UR2S+UH2	
21x+C25x=C29x	
118155-118155-11	
2.* TEO.* 10.* CS TRO. S CS TRO.	

UR2SS=UB2SS.01*UB2*e.2 UR2SS=UB2SS.01*UB2*e.2 UGS=UGS+UG UGS=UGS+UG UGS=UGS+UG UGSS=UGS+UG UGSS=UGS+UGS+UG UGSS=UGS+UGS+UG UGSS=UGS+UG UGSS=UGS+UGS+UG UGSS=UGS+UGS+UG UGSS=UGS+UGS+UGS+UG UGSS=UGS+UG	1		
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APPENDIX E

Definition of Variables Used in CVA Program

A Common Array

alt Aircraft Altitude Above Sea Level - Ft.

alt₁ Altitude Boundary on Turbulence - Ft.

B Common Storage Array

CTERM Periodic Amplitude of Sinusoidal Airwake Terms

DT Time Increment - Sec.

DTOT Nondimensionalized Time Increment of u Burble Component

DTOTW Nondimensionalized Time Constant of W Burble Component

DT2 Time Increment - Second

FacW Extrapolation Factor of Airwake Velocity

FacY Extrapolation Function in Y Direction

FacZ Extrapolation Function in Z Direction

FC Shift Frequency - Cycle/Sec.

FRT Maximum Gust Frequency - Rad./Sec.

FRTD Frequency of Vertical Discrete Gust - Rad./Sec.

FRTE Frequency of East Discrete Gust - Rad./Sec.

FRTN Frequency of North Discrete Gust - Rad./Sec.

GA Common Storage Array

GR Array Containing Turbulence Gains

HIS Steady Deck Height Above Sea Level - Ft.

I Integer Counter

Ia Integer Common Array

IB Integer Common Array

IBFRZ Constant Range Flag

IDISCT Discrete Turbulence Flag

ILBURB Downwash Selection Switch

ILTURB Free Air Turbulence Switch

IMode Operating Mode Switch

Ionce Turbulence Initialization Option Switch

IPitch Ship Pitch Flag

IRDSI Start Up Array

IRDST Start Up Array IuBT Switch for u Burble Component IVBT Switch for V Burble Component IWBT Switch for W Burble Component Iwind Turbulence Selection Switch IX Random Number Startup Parameter OMEGP Ship Pitch Frequency - Rad/Sec. Phase Discrete Turbulence Phase - Rad. PHIP Ship Pitch Phase - Rad. 3.14159 PI PITCHM Ship Pitch Magnitude - Deg. PITCHMI Ship Pitch Magnitude - Rad. RAV Averaging Parameter RD Filtered Output of Random Number Generator RDA Time Constant of Random Number Filter - 1/Sec. RDX Raw Output of Random Number Generator RDY Intermediate Random Number Value RDYI Intermediate Random Number Value RD3 Intermediate Turbulence Variable RD4 Intermediate Turbulence Variable RD5P Intermediate Turbulence Variable RK10 Turbulence Filter Gain RN1 Radar Noise Gain SIN WCT Frequency Shifting Function STHETR Sine of Ship Heading Angle SuBSW Steady u Burble Scale Factor SuB2 Random u Burble RMS Magnitude SwBSW Steady w Burble Scale Factor S110 Filter Parameter S210 Filter Parameter TDTURB Discrete Turbulence Switch Time - Sec.

TIME Simulation Running Time - Sec.

TuB2 Random u Burble Time Constant - Sec.

T11 - T33 Euler Angle Conversion Matrix Relating Aircraft Body Axes

and Inertial Axes

u Output of Random Number Generator

uBSS Steady u Component of Burble - Ft./Sec. UBSS1 Intermediate Turbulence Variable UBT u-Body Axis Burble Component - Ft./Sec. uB1 X-Ship Axis Periodic Burble - Ft./Sec. uB1A Intermediate Variable uB1K Intermediate Variable uB1S Statistical Summary Variable uB1SS Statistical Summary Variable uB1ST Statistical Summary Variable uB2 Ship X Axis Random Burble Component - Ft./Sec. uB2P Intermediate Variable uB2S Statistical Summary Variable uB2SS Statistical Summary Variable uB2ST Statistical Summary Variable uB2TA Statistical Summary Variable uG Aircraft X-Axis Free Air Turbulence Component - Ft./Sec. uGS Statistical Summary Variable uGSA Statistical Summary Variable uGSS Statistical Summary Variable uGST Statistical Summary Variable uTURB Total Aircraft X-Axis Turbulence - Ft./Sec. VBT Lateral Burble Velocity - Ft./Sec. VDBR Vertical Burble Component - Ft./Sec. **VDTURB** Vertical Turbulence Velocity - Ft./Sec. VEBR East Component of Burble - Ft./Sec. VEQIC Aircraft Trim Velocity - Knots VEQICP Previous Trim Velocity - Knots VETURB East Component of Turbulence - Ft./Sec. VG Aircraft Y-Axis Component of Free Air Turbulence - Ft./Sec. VGS Statistical Summary Variable VGSA Statistical Summary Variable VGSS Statistical Summary Variable VGST Statistical Summary Variable Intermediate Variable VG1 VG2 Intermediate Variable VG3 Intermediate Variable

VG4 Intermediate Variable

VMD Vertical Discrete Gust Magnitude - Ft./Sec.

VME East Discrete Gust Magnitude - Ft./Sec.

VMN North Discrete Gust Magnitude - Ft./Sec.

VNBR North Burble Component - Ft./Sec.

VNTURB North Turbulence Component - Ft./Sec.

VO Trim Velocity - Ft./Sec.

VRW Aircraft Airspeed - Ft./Sec.

VS Relative Wind Over Deck Speed - Ft./Sec.

VSD Burble Propagation Speed - Ft./Sec.

VTURB Aircraft Y Axis Component of Total Turbulence - Ft./Sec.

VXBR Ship X Axis Component of Burble - Ft./Sec.
VYBR Ship Y Axis Component of Burble - Ft./Sec.

WBSS Steady Downwash Velocity - Ft./Sec.

WBSS1 Intermediate Variable

WBT Aircraft Z Axis Component of Burble - Ft./Sec.
WB1 Periodic Component of Ship Downwash - Ft./Sec.

WBIA Statistical Summary Variable - Ft./Sec.

WBIK Intermediate Variable

WB1S Statistical Summary Variable
WB1SS Statistical Summary Variable
WB1ST Statistical Summary Variable

WB2 Vertical Random Burble Component - Ft./Sec.

WB2P Intermediate Variable

WB2S Statistical Summary Variable
WB2SS Statistical Summary Variable
WB2ST Statistical Summary Variable
WB2TA Statistical Summary Variable

WC Frequency Shift Parameter - Rad./Sec.
WG Aircraft Z-Axis Free Air Turbulence

WGS Statistical Summary Variable
WGSA Statistical Summary Variable
WGSS Statistical Summary Variable
WGST Statistical Summary Variable

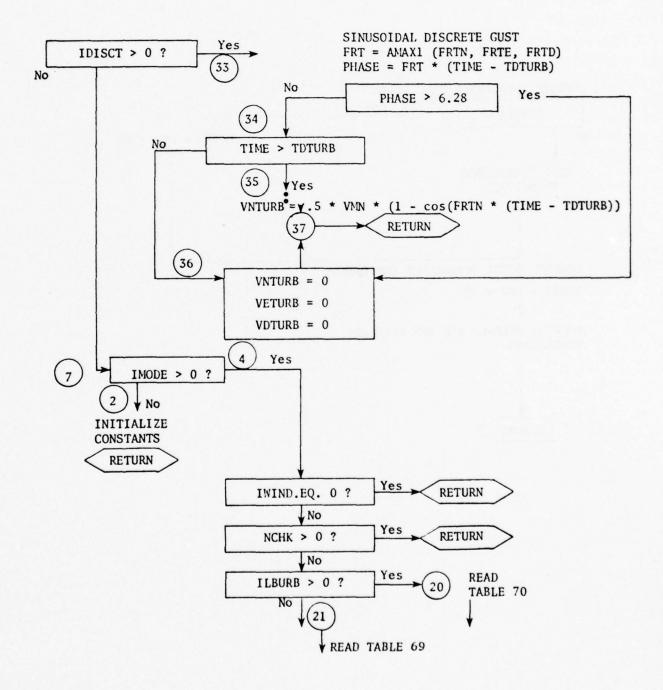
WTURB Aircraft Z-Axis Turbulence Velocity - Ft./Sec.

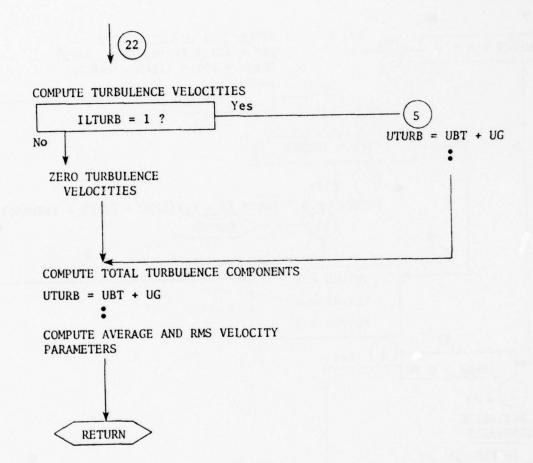
XCG Aircraft X Position Relative to Ship cg - Ft.

XD .	X-Position Variable Used in Table Look Up - Ft.
XFRZ	Fixed Position Used in Table Look Up - Ft.
X1S	Forward Turbulence Limit - Ft.
X2S	Forward Turbulence Limit - Ft.
YCG	Aircraft Lateral Position Relative to Ship - Ft.
YR	Lateral Radar Error - Ft.
YRS	Statistical Summary Variable
YRSA	Statistical Summary Variable
YRSS	Statistical Summary Variable
YRST	Statistical Summary Variable
YRL	Scale Factor on Radar Noise Function
YR2	Scale Factor on Radar Noise Function
ZI1	Turbulence Filter Parameters
ZI111	Turbulence Filter Parameters
ZI112	Turbulence Filter Parameters
ZI2	Turbulence Filter Parameters
ZI3	Turbulence Filter Parameters
ZI4	Turbulence Filter Parameters
Z01	Turbulence Filter Parameters
Z0111	Turbulence Filter Parameters
Z0112	Turbulence Filter Parameters
Z02	Turbulence Filter Parameters
ZR	Vertical Radar Noise - Ft.
ZRS	Statistical Summary Parameter
ZRSA	Statistical Summary Parameter
ZRSS	Statistical Summary Parameter
ZRST	Statistical Summary Parameter
ZR1	Radar Noise Parameter
ZR2	Radar Noise Parameter

APPENDIX (

Flow Chart for CVA Model





APPENDIX D

Listing of FF 1052 Turbulence Subroutine

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APPENDIX E

Variable Definitions for FF 1052 Program

A Common Array

ALT Altitude of Aircraft cg Above Sea Level - Ft.

B Common Array

Beam Ship Beam - Ft.

CPSIREL Cosine of Relative Wind Angle
CPSISR Cosine of Ship Heading Angle

CPSIW Cosine of Absolute Wind Direction

DT Integration Frame Time - Sec.

DTW Integration Frame Time of Turbulence Subroutine - Sec.

DTX Update Time Increment of X-Random Number Generator - Sec.

DTY Update Time Increment of Y Component Random Number Generator

DTZ Update Increment of Z Component Random Number Generator

EXPY X Component Difference Equation Parameter
EXPY Y Component Difference Equation Parameter

EXPZ Z Component Difference Equation Parameter

FOMEGY X Frequency Extrapolation Function
FOMEGY Y Frequency Extrapolation Function
FX1 X Direction Extrapolation Function
FY1 Y Direction Extrapolation Function

FZ1 Z Direction Extrapolation Function

F1 Total Extrapolation Function

HTD Height of Touchdown Point Above Sea Level - Ft.

IA Integer Common Array

IB Integer Common Array

IMODE Simulation Mode Switch

IONCE Random Number Startup Option Switch

IRDSTX Initial Value of X - Random Number Sequence
IRDSTXI Current Value of X - Random Number Sequence
IRDSTY Initial Value of Y - Random Number Sequence
IRDSTYI Current Value of Y - Random Number Sequence

IRDSTZ Initial Value of Z - Random Number Sequence

IRDSTZI Current Value of Z - Random Number Sequence

IWIND Turbulence on/off Flag

IX Machine Dependent Random Number Generator Parameter

OMEGY X - Component Filter Constant
OMEGY Y - Component Filter Constant
OMEGZ Z - Component Filter Constant

PI 3.14159

PSIREL Angle of Relative Wind With Respect to Ship - Rad.

PSIS Ship Heading - Deg.
PSISR Ship Heading - Rad.

PSIW Absolute Wind Direction - Rad.

RANDX Interpolated Value of X - Component Random Number Generator

RANDXN Current Output of X - Random Number Generator

RANDXO Previous Output of Y - Component Random Number Generator
RANDY Interpolated Value of Y Component Random Number Generator

RANDYN Current Output of Y Random Number Generator

RANDYO Previous Output of Y Random Number Generator

RANDZ Interpolated Value of Z Component Random Number Generator

RANDZN Current Output of Z Random Number Generator
RANDZO Previous Output of Z Random Number Generator

RLS Ship Length - Ft.

RLTD Distance From Bow to Touchdown Point - Ft.

RMODE Mode Parameter

RNX X Component Time Increment Ratio
RNY Y Component Time Increment Ratio
RNZ Z Component Time Increment Ratio
SIGVX X Velocity Variance - Ft./Sec.
SIGVY Y Velocity Variance - Ft./Sec.

SIGVZ Z Velocity Variance - Ft./Sec.

SIGX Tabulated X Component Variance - Ft./Sec.

SIGY Tabulated Y Component Variance - Ft./Sec.

SIGZ Tabulated Z Component Variance - Ft./Sec.

SLOPEX X Extrapolation Parameter

SLOPE1 X Boundary Definition Parameter
SPSIREL Sine of Relative Heading Angle

SPSISR Sine of Ship Heading

SPSIW Sine of Wind Heading

TCOUNT Update Time Counter - Sec.

TCOUNTY X Update Time - Sec.

TCOUNTY Y Update Time - Sec.

TCOUNTZ Z Update Time - Sec.

TFAC Turbulence Update Paramater

TIME Simulation Time - Sec.

VDTN Current Value of Vertical Turbulence Component - Ft./Sec.

VDTO Previous Value of Vertical Turbulence Component - Ft./Sec.

VDTURB Interpolated Value of Vertical Turbulence - Ft./Sec.

VDW Total Vertical Wind Including Free Air Wind - Ft./Sec.

VETN Current Value of Computed East Turbulence Component - Ft./Sec.

VETO Previous Value of Vertical Turbulence Component - Ft./Sec.

VETURB Interpolated Value of East Turbulence - Ft./Sec.

VEW Total East Wind - Ft./Sec.

VEWBIC Initial East Wind Component - Ft./Sec.

VNTN Current North Turbulence Update - Ft./Sec.

VNTO Previous North Turbulence Update - Ft./Sec.

VNTURB Interpolated North Turbulence Component - Ft./Sec.

VNW North Wind Component - Ft./Sec.

VNWBIC Initial North Wind Component - Ft./Sec.

VS Ship Speed - Ft./Sec.

VW Total Steady Wind - Ft./Sec.

VW1 Velocity Ratio

VXBar Mean X Turbulence Velocity - Ft./Sec.

VXT Random X Component of Turbulence - Ft./Sec.

VXTP Previous Value of VXT - Ft./Sec.

VXTURB Total X Component of Turbulence - Ft./Sec.

VXWS Tabulated Mean X Velocity Component - Ft./Sec.

VYBar Mean Y Turbulence Velocity - Ft./Sec.

VYT Random Y Component of Turbulence - Ft./Sec.

VYTP Previous Value of VYT - Ft./Sec.

VYTURB Total Y Component of Turbulence - Ft./Sec.

VYWS Tabulated Mean Y Velocity Component - Ft./Sec.

VZBar Z Component Mean Turbulence Velocity - Ft./Sec.

VZT Z Component of Random Turbulence - Ft./Sec.

VZTP Previous Value of VZT - Ft./Sec.

VZTURB Total Z Component of Turbulence - Ft./Sec.

VZWS Tabulated Mean Z Turbulence Velocity - Ft./Sec.

XE North - South Distance From Aircraft cg to Touchdown Pt. - Ft.

XMIN Forward Limit on Turbulence Region - Ft.

XMIN1 Intermediate Value of XMIN - Ft.
XMIN2 Intermediate Value of XMIN - Ft.

XTaB X Table Lookup Parameter - Ft.

XWIND Aircraft Position Measured Parallel to Relative Wind - Ft.

YE Aircraft East - West Position Relative to Touchdown Point - Ft.

YMAX Right Limit on Turbulence - Ft.

YMAX1 Intermediate Value of YMAX - Ft.

YMIN Left Limit on Turbulence - Ft.

YMIN1 Intermediate Value of YMIN - Ft.

YTaB Y Table Lookup Parameter

YWIND Aircraft Position Relative to Touchdown Point Measured Transverse

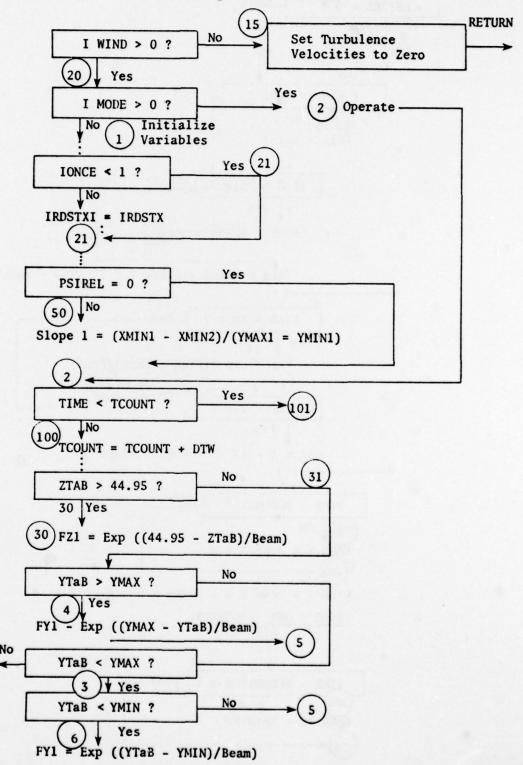
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ZTaB Z Table Lookup Parameter - Ft.

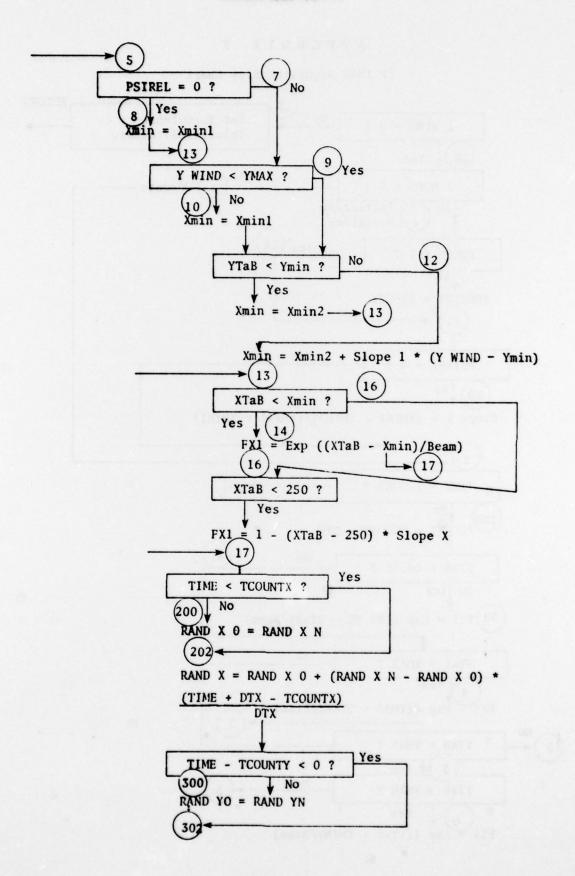
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APPENDIX F

FF 1052 Algorithm Flow Chart



S. Almara weeks



RAND Y = RAND YO + (RAND YN - RAND YO) * (TIME + DTY - TCOUNTY)/DTY TIME - TCOUNTZ < 0 ? No (400)RAND ZO = RAND ZN RAND ZN = RAND ZO + (RAND ZN - RAND ZO) * (TIME + DTZ - TCOUNTZ)/DTZ XTaB ≤ 18 ? Yes 500 FOMEGX = 1.0No XTaB < 190 ? Yes 502) FOMEGX = 1 - .0042777 * XTaB (503)FOMEGX = .1935(504)(101)_{No} IMODE = -1 ?Yes VNTO = VNTN TFAC = (TIME + DTW - TCOUNT)/DTW Return End

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